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CANINE

Computer Analysis of Networks via Inversion of Network Equations

by

Paul M. Russo

Memorandum No. ERL-M252

22 August 1968

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(over)

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ERRATA

Corrections to listing of CANINE:

ERL-M252

SUBROUTINE PT:

Card C-246 should read

IF (KKTT, EO.1) go to 62

Card C-253 should be replaced by the following three cards:

I = NN - 1

DO 35 J = NN, NB

I = I + 1

The following card should be added right after C-257

62 I = I - 1

Comment on use of CANINE:

CANINE will not, in general, handle the following situations:

1. Compatible loops of voltage sources containing voltage controlled voltage sources.
2. Compatible cutsets of current sources containing current controlled current sources.

The above situations give rise to a singular \underline{A} matrix, and no diagnostic is provided. For such problems, the use of CANDO⁽¹⁾ is recommended.

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ABSTRACT

This report describes the operation and use of CANINE (Computer Analysis of Networks via Inversion of Network Equations), a time-domain analysis program, for linear time-invariant networks. The networks may contain dependent and independent sources of all types, capacitances, resistances and inductances.

The network analysis problem is to obtain the branch currents and voltages by solving a set of simultaneous differentio-algebraic equations derived from the branch relations and Kirchhoff's current and voltage laws.

In the program CANINE, tree voltages and link currents form a basis set of variables, denoted by \underline{x} . This formulation yields the automatic satisfaction of Kirchhoff's laws. A numerical integration formula reduces the system to a set of simultaneous algebraic equations of the form

$$\underline{A} \underline{x} = \underline{k},$$

where \underline{A} is called the "network equation matrix" and \underline{k} is a vector, which is constant at any time point, and which will be defined later.

The solution \underline{x} is obtained by inverting the matrix \underline{A} :

$$\underline{x} = \underline{A}^{-1} \underline{k}.$$

The tree-picking and internal current scaling algorithms are such that large value spread and large time constant spread problems can be handled reasonably effectively and efficiently.

The program CANINE is written in Fortran IV for the CDC
6400 computer operating under the (CAL) Scope 3.1 system.

ACKNOWLEDGEMENTS

I wish to acknowledge the constant encouragement and motivating influence of Professor R. A. Rohrer, without whose guidance the writing of this report would have never taken place.

I also wish to acknowledge the financial support of the Air Force Office of Scientific Research, under Grant AF-AFOSR-1219-67, and the Computer Center of the University of California at Berkeley, which has been most gracious in its granting of subsidized computer time.

INTRODUCTION

Since the program CANINE evolved from the program CANDO⁽¹⁾, many of the subroutines making up CANINE are identical to those of program CANDO.

The following subroutines are common to both programs and are described in (1);

Subroutine	READIN
Subroutine	PT
Subroutine	FCSM
Subroutine	KONST
Subroutine	CALCAL
Subroutine	INCREM
Subroutine	PERIOD
Subroutine	READOUT
Subroutine	GRAPH
Subroutine	ALLOUT

Knowledge of the operation of the above subroutines is not necessary for the effective use of program CANINE.

It should be noted, at this point, that programs CANINE and CANDO are complementary in the sense that each is better suited to a particular type of network analysis. If an exact analysis is desired, CANINE has been found to be the superior (in the sense of computer time) whereas, if only an approximate analysis is desired (as in the

initial stages of automated network design), CANDO, due to its iterative formulation, is the more desirable program.

The choice of either program over the other must depend on the type of analysis that the user finds most desirable, for his particular application.

Section I describes the formulation of the matrix \underline{A} and the vector \underline{k} . Section II describes the main program and subroutines associated with CANINE which have not been employed in the program CANDO. The Appendices describe the use of CANINE in solving network problems, and the way dependent sources must be modeled.

SECTION I: NETWORK ANALYSIS

Theory:

The solution of a network consists of finding the branch current and voltage vectors \tilde{i}_b and \tilde{v}_b respectively. The solution is obtained by solving the following simultaneous set of equations

$$\tilde{f}_b(\tilde{i}_b, \tilde{v}_b) = \tilde{0} \text{ branch relations}$$

$$\tilde{Q} \tilde{i}_b = \tilde{0} \text{ Kirchhoff's current law}$$

$$\tilde{B}' \tilde{v}_b = \tilde{0} \text{ Kirchhoff's voltage law}$$

where \tilde{Q} is the fundamental cutset matrix, and \tilde{B} is the fundamental loop matrix based on an appropriately selected tree. We may renumber the NB branches of our network in such a way that the 1st NN-1 (where NN is the number of nodes in our network) branches form the tree.

With the above numbering scheme, \tilde{Q} and \tilde{B} may be partitioned as follows:

$$\tilde{Q} = \left[\tilde{I} : \tilde{F} \right] \quad \text{and} \quad \tilde{B} = \left[\begin{array}{c} -\tilde{F}' \\ \tilde{I} \end{array} \right]$$

and hence we have, from Kirchhoff's laws

$$\tilde{i}_t = -\tilde{F} \tilde{i}_l$$

$$\tilde{v}_l = \tilde{F}' \tilde{v}_t$$

where the subscripts t and l refer to tree branches and links respectively. Our tree picking algorithms are discussed in subroutine PT⁽¹⁾, suffice it to say that in both our tree-picking schemes,

independent voltage sources must be tree branches and independent current sources must be links. Upon using a numerical integration formula (see subroutine MATSET), our set of equations reduces to

$$\underline{\underline{L}}(\underline{\underline{v}}_t, \underline{\underline{i}}_l) = \underline{\underline{0}}.$$

This set of linear equations is solved by reducing it to the form

$\underline{\underline{A}} \underline{\underline{x}} = \underline{\underline{k}}$ (see subroutine MATSET) where

$$\underline{\underline{x}} = \begin{bmatrix} \underline{\underline{v}}_t \\ \underline{\underline{i}}_l \end{bmatrix}$$

and inverting $\underline{\underline{A}}$ to yield

$$\underline{\underline{x}} = \underline{\underline{A}}^{-1} \underline{\underline{k}}.$$

The solution obtained by CANINE is exact and is limited only by roundoff error in the computer and the accuracy of the integration formula.

Solving the Initial Condition Problem:

Given the initial capacitance voltages and inductance currents, we wish to compute $\underline{\underline{v}}_1$ and $\underline{\underline{i}}_1$, the branch voltages and currents, at the initial time point. This reduces to the problem of solving a coupled system of algebraic equations.

A proper tree is selected according to the algorithm described in subroutine PT⁽¹⁾. This algorithm maximizes the number of capacitances in tree branches and the number of inductances in links.

If there are no capacitance or capacitance-voltage source loops, or inductance or inductance-current source cutsets, all capacitances will be tree branches, and all inductances will be links.

Kirchhoff's current and voltage laws become automatically satisfied by selecting the tree voltages and link currents to be a basis set of variables, with the following being true

$$\tilde{i}_{t_1} = -\tilde{F} \tilde{i}_{l_1}$$

and

$$\tilde{v}_{l_1} = \tilde{F}' \tilde{v}_{t_1},$$

where the subscripts l and t refer to links and tree branches respectively, and where $\tilde{Q} = \left[\tilde{I} : \tilde{F} \right]$ is the fundamental cutset matrix based on the proper tree.

Tree capacitances are treated as independent voltage sources with their voltage being set to the initial condition. Similarly, link inductances are treated as independent current sources with their current being set to the initial condition. Tree inductance voltages and link capacitance currents are set equal to zero, and their initial conditions are lost. Hence, incompatible initial conditions (e. g., incompatible capacitance voltages around a capacitance-voltage source loop or incompatible inductor currents at an inductor-current source cutset) are forced to be compatible, with the tree inductances and link capacitances losing their specified initial conditions.

Except for the fact that reactive elements are treated as independent sources, the solution of the initial condition problem is

analogous to that of the "general time point problem," and will not be detailed here. Suffice it to say that our system of equations is reduced to the form

$$\underline{\underline{A}} \underline{\underline{x}} = \underline{\underline{k}}$$

and the solution is obtained, via the inversion of $\underline{\underline{A}}$, from

$$\underline{\underline{x}} = \underline{\underline{A}}^{-1} \underline{\underline{k}},$$

where

$$\underline{\underline{x}} = \begin{bmatrix} \underline{\underline{v}}_{t_1} \\ \underline{\underline{i}}_{t_1} \end{bmatrix} .$$

Solving the General Time Point Problem:

Knowing $\underline{\underline{i}}_{t_1}$ and $\underline{\underline{v}}_{t_1}$, the branch currents and voltages at the previous time point, we wish to compute $\underline{\underline{i}}$ and $\underline{\underline{v}}$, the branch currents and voltages at the succeeding time point. The problem reduces to solving the coupled system of differential and algebraic equations, consisting of the branch relations, and Kirchhoff's current and voltage laws.

A tree is selected according to the optimal tree algorithm of subroutine PT⁽¹⁾, rendering the system well behaved, and hence minimizing computational errors in our matrix inversion scheme. The network is renumbered such that the first NN-1 branches form the tree, and the subsequent branches are links. Kirchhoff's current and voltage laws become automatically satisfied by selecting the tree

voltages and link currents as a basis set of variables. Note that this approach requires that independent voltage sources be tree branches and that independent current sources be links.

The tree currents \tilde{i}_t are given, in terms of the link currents \tilde{i}_l by

$$\tilde{i}_t = -\tilde{F} \tilde{i}_l,$$

where $\tilde{Q} = \begin{bmatrix} \tilde{I} & \tilde{F} \end{bmatrix}$ is the fundamental cutset matrix associated with our optimal tree. Similarly,

$$\tilde{v}_l = \tilde{F}' \tilde{v}_t,$$

where \tilde{F}' is the transpose of \tilde{F} .

The problem thus reduces to solving the set of equations

$$\tilde{f}(\tilde{v}_t, \dot{\tilde{v}}_t, \tilde{i}_t, \dot{\tilde{i}}_t) = \tilde{0}$$

Integrating the above set of equations, via a numerical integration formula, reduces the problem to

$$L(\tilde{v}_t, \tilde{i}_l) = \tilde{0},$$

where the L_i are the general time point branch relations, in terms of our basis set of variables. The above set of equations is reduced to the form

$$\tilde{A} \tilde{x} = \tilde{k},$$

and the solution is obtained, explicitly, from

$$\underset{\sim}{x} = \begin{bmatrix} \underset{\sim}{v}_t \\ \text{-----} \\ \underset{\sim}{i}_l \end{bmatrix} = \underset{\sim}{A}^{-1} \underset{\sim}{k}.$$

Construction of $\underset{\sim}{A}$ and $\underset{\sim}{k}$:

We wish to solve a set of branch relations of the form

$$\underset{\sim}{f}(\underset{\sim}{v}_b, \underset{\sim}{i}_b) = \underset{\sim}{0} \quad (1)$$

while simultaneously satisfying Kirchhoff's voltage and current laws.

Upon the selection of a tree, and appropriate renumbering, Kirchhoff's voltage and current laws may be expressed as

$$\left. \begin{aligned} \underset{\sim}{v}_l &= \underset{\sim}{F}' \underset{\sim}{v}_t \\ \underset{\sim}{i}_t &= -\underset{\sim}{F} \underset{\sim}{i}_l \end{aligned} \right\} \quad (2)$$

where the subscripts t and l refer to tree branches and links, respectively, and

$$\underset{\sim}{Q} = \left[\underset{\sim}{I} : \underset{\sim}{F} \right]$$

is the fundamental cutset matrix based on our topological tree.

Substituting (2) into (1), we obtain

$$\underset{\sim}{L}(\underset{\sim}{v}_t, \underset{\sim}{i}_l) = \underset{\sim}{0} \quad (3)$$

We wish to reduce (3) to the form

$$\underset{\sim}{A} \underset{\sim}{x} = \underset{\sim}{k} \quad (4)$$

where

$$\tilde{x} = \begin{bmatrix} \tilde{v}_t \\ \tilde{i}_l \end{bmatrix} \quad (5)$$

and hence the solution is given by

$$\tilde{x} = \tilde{A}^{-1} \tilde{k} \quad (6)$$

Note that \tilde{A} is an $NB \times NB$ nonsingular matrix, where NB is the number of branches in the network.

Upon the inclusion of a numerical integration formula, the i th general branch relation can be written in the form

$$-\alpha_i \cdot i_i + \beta_i \cdot v_i - C_i \cdot i_m - l_i \cdot v_m = k_i \quad (7)$$

The C_i and l_i terms are nonzero only for dependent sources, and m designates the controlling branch.

Tree Branches:

NN designates the number of nodes, $P = NN - 1$, and $const_i$ designates the branch constant as computed in subroutine KONST (1).

H denotes the integration step size.

Independent Voltage Sources:

branch relation

$$v_i = \text{source value}$$

Thus $\alpha_i = C_i = l_i = 0$

$$\beta_i = 1$$

$$k_i = \text{source value}$$

$$\text{so } A_{ij} = \delta_{ij} \text{ (Kronecker delta)}$$

$$= 1 \quad i = j$$

$$= 0 \quad i \neq j$$

Dependent Voltage Source:

a) voltage controlled (controlling voltage is a link voltage).

branch relation:

$$v_i - \text{const}_i \cdot v_m = 0$$

$$\text{Thus } \alpha_i = C_i = k_i = 0$$

$$\beta_i = 1$$

$$l_i = \text{const}_i$$

since v_m is a link voltage, we must express it in terms of tree voltages,

i. e.,

$$v_m = \sum_K F'_{m-P,K} \cdot v_K$$

over tree
branches

$$\text{so } A_{ij} = 0 \quad j \geq NN$$

$$A_{ij} = \delta_{ij} - F'_{j,m-P} \cdot \text{const}_i \quad j < NN$$

b) current controlled (controlling current is a tree current).

branch relation:

$$v_i - \text{const}_i \cdot i_m = 0$$

thus $\alpha_i = l_i = k_i = 0$

$$C_i = \text{const}_i$$

$$\beta_i = 1$$

since i_m is a tree current, we must express it in terms of link currents, i. e.,

$$i_m = - \sum_{\substack{K \\ \text{over links}}} F_{mK} \cdot i_K$$

so, $A_{ij} = \delta_{ij} \quad j < NN$

$$A_{ij} = \text{const}_i \cdot F_{m, j-P} \quad j \geq NN$$

Tree Capacitances:

a) initial time point problem

branch relation:

$$v_i = \text{initial condition}$$

Thus $\alpha_i = C_i = l_i = 0$

$$\beta_i = 1$$

$$k_i = \text{initial condition}$$

so $A_{ij} = \delta_{ij}$

b) general time point problem

Let 1 designate the previous time point and 2 designate the present time point. A trapezoidal numerical integration formula is employed.

branch relation:

$$v_{i2} - \text{const}_i i_{i2} = \text{const}_i \cdot i_{i1} + v_{i1}$$

Thus $k_i = \text{const}_i \cdot i_{i1} + v_{i1}$

$$l_i = C_i = 0$$

$$\beta_i = 1$$

$$\alpha_i = \text{const}_i$$

Now i_{i2} must be expressed in terms of link currents, i. e.,

$$i_{i2} = - \sum_K F_{iK} \cdot i_{2K}$$

over links

so $A_{ij} = \delta_{ij} \quad j < NN$

$$A_{ij} = \text{const}_i \cdot F_{i,j-P} \quad j \geq NN$$

Tree Resistance:

branch relation:

$$v_i - \text{const}_i \cdot i_i = 0$$

Thus $\alpha_i = \text{const}_i$

$$\beta_i = 1$$

$$C_i = l_i = k_i = 0$$

We must express i_i in terms of link currents, i. e.,

$$i_i = - \sum_K F_{iK} \cdot i_K$$

over links

so, $A_{ij} = \delta_{ij} \quad j < NN$

$$A_{ij} = \text{const}_i \cdot F_{i,j-P} \quad j \geq NN$$

Tree Inductances:

a) initial time point problem

Due to our selection of a proper tree, the initial voltage across a link inductance is taken to be zero.

branch relation:

$$v_i = 0$$

$$\text{Thus } \alpha_i = C_i = l_i = k_i = 0$$

$$\text{so } A_{ij} = \delta_{ij}$$

b) general time point problem

Let 1 designate the previous time point and 2 designate the present time point. A trapezoidal numerical integration formula is employed.

branch relation:

$$v_{i2} - \text{const}_i \cdot i_{i2} = -v_{i1} - \text{const}_i \cdot i_{i1}$$

$$\text{thus } \alpha_i = \text{const}_i$$

$$\beta_i = 1$$

$$C_i = l_i = 0$$

$$k_i = -v_{il} - \text{const}_i \cdot i_{il}$$

We must express i_{i2} in terms of link currents, i. e.,

$$i_{i2} = - \sum_K F_{iK} \cdot i_{2K}$$

over links

$$\text{so } A_{ij} = \delta_{ij} \quad j < NN$$

$$A_{ij} = \text{const}_i \cdot F_{i,j-P} \quad j \geq NN$$

Dependent Current Sources:

a) voltage controlled (controlling voltage is a link voltage).

branch relation:

$$i_i - \text{const}_i \cdot v_m = 0$$

$$\text{thus } \alpha_i = -1$$

$$\beta_i = C_i = k_i = 0$$

$$l_i = \text{const}_i$$

We must express v_m in terms of tree voltages, and i_i in terms of link currents, i. e.,

$$v_m = \sum_K F'_{m-P,K} \cdot v_K$$

over tree
branches

$$i_i = - \sum_K F_{iK} \cdot i_K$$

over links

$$\text{so } A_{ij} = -F_{j,m-P} \text{ const}_i \quad j < NN$$

$$A_{ij} = -F_{i,j-P} \quad j \geq NN$$

b) current controlled (controlling current is a tree current).

branch relation:

$$i_i - \text{const}_i \cdot i_m = 0$$

$$\text{thus } \alpha_i = -1$$

$$\beta_i = \ell_i = k_i = 0$$

$$C_i = \text{const}_i$$

Both i_i and i_m are tree currents and must be expressed in terms of link currents, i. e.,

$$i_i = - \sum_{\substack{K \\ \text{over links}}} F_{iK} \cdot i_K, \quad i_m = - \sum_{\substack{K \\ \text{over links}}} F_{mK} \cdot i_K$$

$$\text{so } A_{ij} = 0 \quad j < NN$$

$$A_{ij} = -F_{i,j-P} + \text{const}_i \cdot F_{m,j-P} \quad j \geq NN$$

Link Branches:

Independent Current Sources:

branch relation:

$$i_i = \text{source value}$$

thus $\alpha_i = -1$

$$\beta_i = C_i = l_i = 0$$

$$k_i = \text{source value}$$

so, $A_{ij} = \delta_{ij}$

Dependent Current Sources:

a) voltage controlled (controlling branch is a link)

branch relation:

$$i_i - \text{const}_i \cdot v_m = 0$$

thus $\alpha_i = -1$

$$\beta_i = C_i = k_i = 0$$

$$l_i = \text{const}_i$$

We must express v_m in terms of tree voltages, i. e.,

$$v_m = \sum_{\substack{K \\ \text{tree branches}}} F'_{m-P, K} \cdot v_K$$

so, $A_{ij} = -F'_{j, m-K} \cdot \text{const}_i \quad j < NN$

$$A_{ij} = \delta_{ij} \quad j \geq NN$$

b) current controlled (controlling branch is a tree branch).

branch relation:

$$i_i - \text{const}_i \cdot i_m = 0$$

thus $\alpha_i = -1$

$$\beta_i = \ell_i = k_i = 0$$

$$C_i = \text{const}_i$$

We must express i_m in terms of link currents, i. e.,

$$i_m = - \sum_K F_{mK} \cdot i_K$$

over links

so, $A_{ij} = 0 \quad j < NN$

$$A_{ij} = \delta_{ij} + F_{m, j-P} \cdot \text{const}_i \quad j \geq NN$$

Link Capacitances:

a) initial time point problem

branch relation:

$$i_i = 0$$

thus $\alpha_i = -1$

$$\beta_i = C_i = \ell_i = k_i = 0$$

so, $A_{ij} = \delta_{ij}$

b) general time point problem

Let the subscripts 1 and 2 designate the previous and present time points respectively. A trapezoidal numerical integration

formula is employed.

branch relation:

$$i_{i2} - \text{const}_i \cdot v_{i2} = - \text{const}_i \cdot v_{i1} - i_{i1}$$

thus $\alpha_i = -1$

$$\beta_i = - \text{const}_i$$

$$C_i = \ell_i = 0$$

$$k_i = - \text{const}_i \cdot v_{i1} - i_{i1}$$

We must express v_{i2} in terms of tree voltages, i. e.,

$$v_{i2} = \sum_{\substack{K \\ \text{tree branches}}} F'_{i-P} \cdot v_{2K}$$

so, $A_{ij} = - F_{j,i-P} \cdot \text{const}_i \quad j < NN$

$$A_{ij} = \delta_{ij} \quad j \geq NN$$

Link Resistance:

branch relation:

$$i_i - \text{const}_i v_i = 0$$

thus $\alpha_i = -1$

$$\beta_i = - \text{const}_i$$

$$C_i = \ell_i = k_i = 0$$

We must express v_i in terms of tree voltages, i. e.,

$$v_i = \sum_{\substack{K \\ \text{tree branches}}} F'_{i-P, K} \cdot v_K$$

$$\text{so, } A_{ij} = -F_{j, i-l} \cdot \text{const}_i \quad j < NN$$

$$A_{ij} = \delta_{ij} \quad j \geq NN$$

Link Inductance:

a) initial time point problem.

branch relation:

$$i_i = \text{initial condition}$$

$$\text{thus } \alpha_i = -1$$

$$\beta_i = C_i = l_i = 0$$

$$k_i = \text{initial condition}$$

$$\text{so, } A_{ij} = \delta_{ij}$$

b) general time point problem.

The subscripts 1 and 2 designate the previous and present time points respectively. A trapezoidal numerical integration formula is used.

branch relation:

$$i_{i2} - \text{const}_i \cdot v_{i2} = i_{i1} + \text{const}_i \cdot v_{i1}$$

$$\text{thus } \alpha_i = -1$$

$$\beta_i = - \text{const}_i$$

$$C_i = l_i = 0$$

$$k_i = i_{il} + \text{const}_i \cdot v_{il}$$

We must express v_{i2} in terms of tree voltages, i. e.,

$$v_{i2} = \sum_{\substack{K \\ \text{tree branches}}} F'_{i-P, K} \cdot v_{2K}$$

$$\text{so, } A_{ij} = - F_{j, i-P} \cdot \text{const}_i \quad j < NN$$

$$A_{ij} = \delta_{ij} \quad j \geq NN$$

Dependent Voltage Sources:

a) voltage controlled (controlling branch is a link).

branch relation:

$$v_i - \text{const}_i \cdot v_m = 0$$

$$\text{thus } \alpha_i = C_i = k_i = 0$$

$$\beta_i = 1$$

$$l_i = \text{const}_i$$

both v_i and v_m must be expressed in terms of tree voltages, i. e.,

$$v_i = \sum_{\substack{K \\ \text{tree branches}}} F'_{i-P, K} \cdot v_K$$

$$v_m = \sum_K F'_{m-P, K} \cdot v_K$$

tree branches

so, $A_{ij} = F_{j, i-P} - F_{j, m-P} \cdot \text{const}_i \quad j < NN$

$A_{ij} = 0.0 \quad j \geq NN$

b) current controlled (controlling branch is a tree branch).

branch relation:

$$v_i - \text{const}_i \cdot i_m = 0$$

thus $\alpha_i = \ell_i = K_i = 0$

$$\beta_i = 1$$

$$C_i = \text{const}_i$$

We must express v_i in terms of tree voltages, and i_m in terms of

link currents, i. e.,

$$v_i = \sum_K F'_{i-P, K} \cdot v_K$$

tree branches

$$i_m = \sum_K F_{m-P, K} \cdot v_K$$

link branches

so, $A_{ij} = F_{j, i-P} \quad j < NN$

$A_{ij} = F_{m-P, j-P} \cdot \text{const}_i \quad j \geq NN$

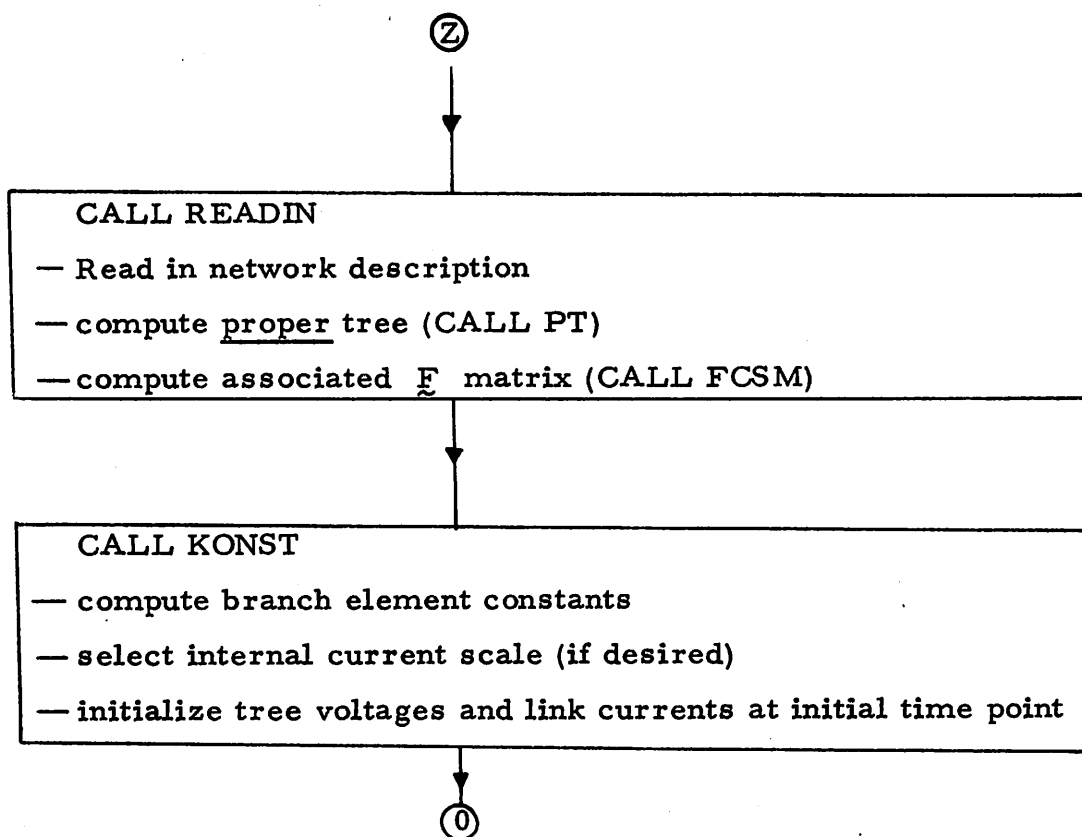
SECTION II

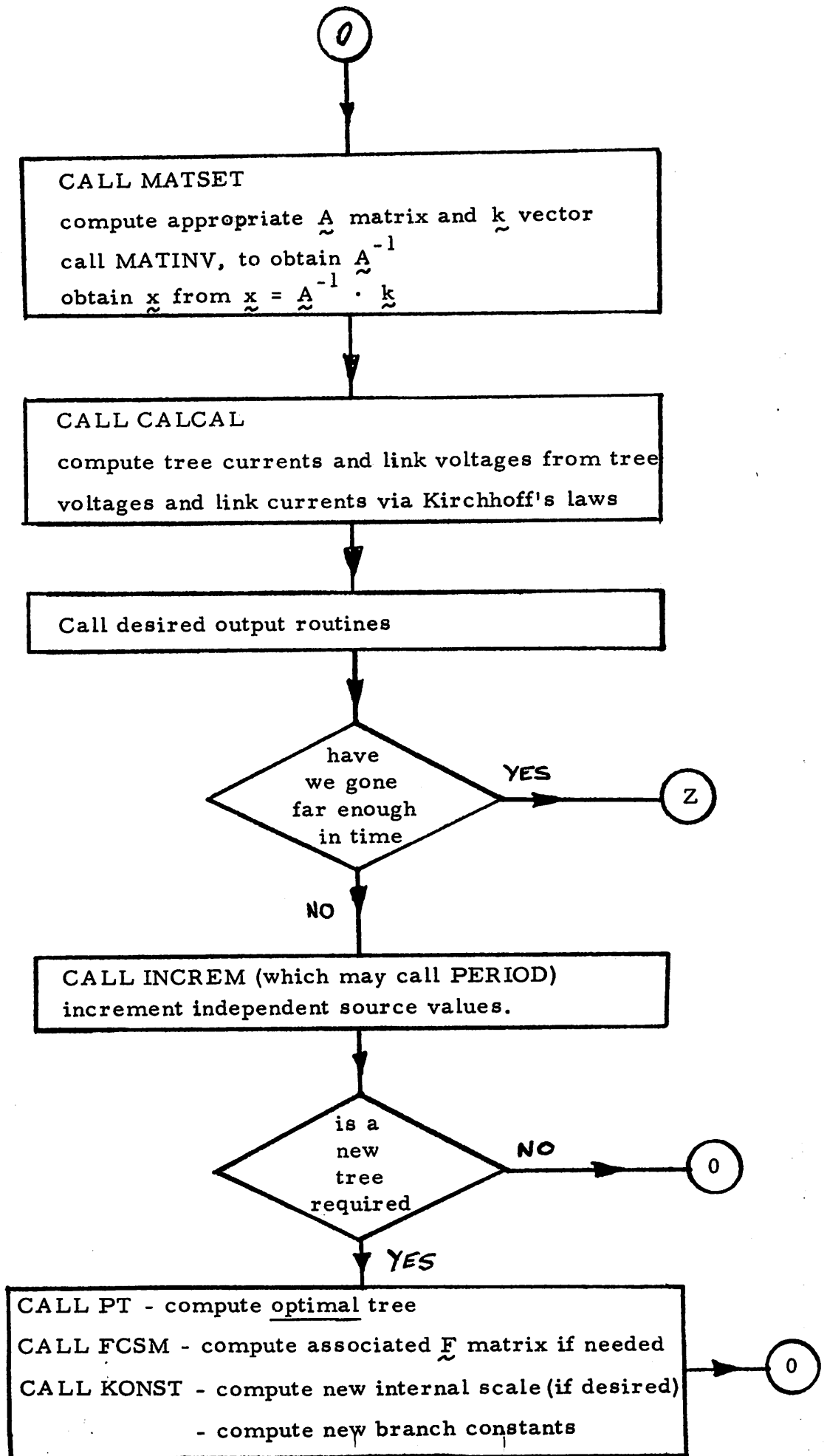
Program CANINE

MAIN program:

The MAIN section of program CANINE ensures that the desired subroutines are called in the correct sequence. It solves both the initial condition and general time point problems, in the way discussed in Section I. It also controls the calls to the output routines.

BLOCK DIAGRAM - MAIN PROGRAM





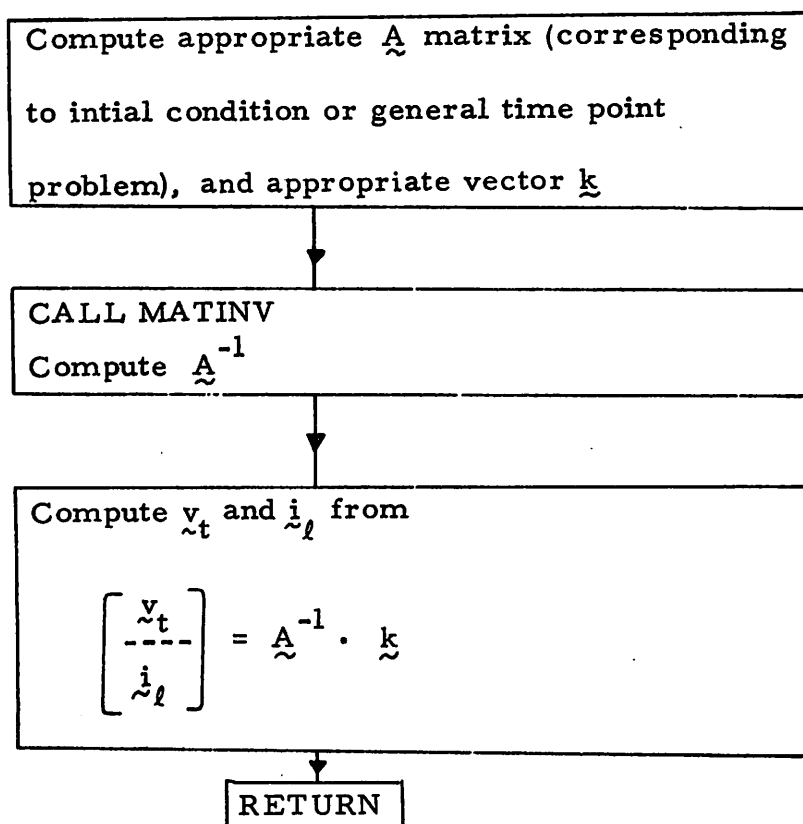
SUBROUTINE MATSET

This subroutine computes the $\underline{\underline{A}}$ matrix and \underline{k} vector for both the initial condition problem and for the general time point problem. MATSET then calls MATINV which computes $\underline{\underline{A}}^{-1}$. The solution is then computed from

$$\begin{bmatrix} \underline{v}_t \\ \underline{i}_l \end{bmatrix} = \underline{\underline{A}}^{-1} \cdot \underline{k}$$

The general operation of this subroutine may be seen below.

BLOCK DIAGRAM - SUBROUTINE MATSET



SUBROUTINE MATINV

This is a standard IBM matrix inversion routine which obtains \underline{A}^{-1} via Gaussian elimination, making use of maximal pivoting.

The original matrix \underline{A} is destroyed in the process, and \underline{A}^{-1} is stored in the place of \underline{A} .

MATINV also computes the determinant of \underline{A} which can be outputted for diagnostic purposes.

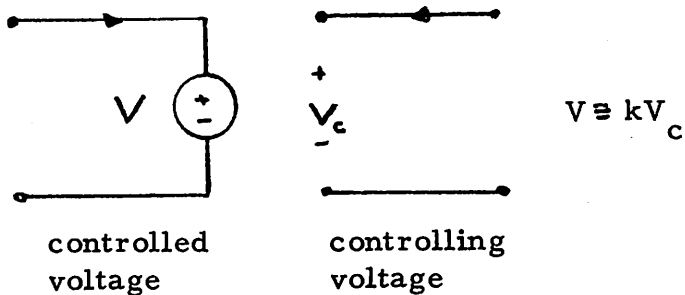
APPENDIX A

Dependent Source Modeling:

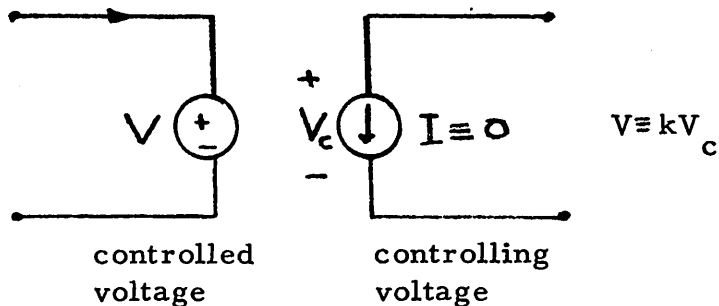
Each dependent source requires two branches for its complete specification, both of which must be a part of the network description, and hence must be read in as data.

Voltage Controlled Voltage Source:

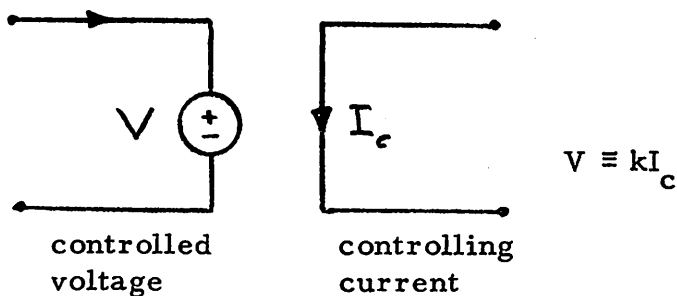
Ideal model:



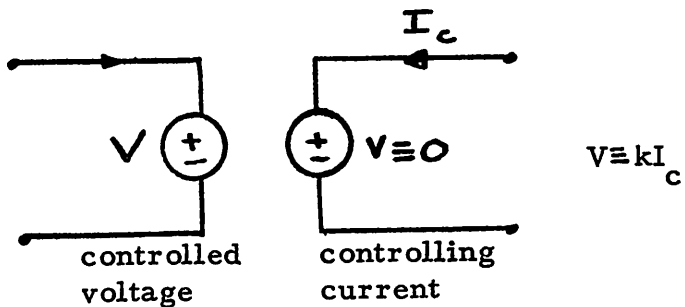
CANINE model:

Current Controlled Voltage Source:

Ideal model:

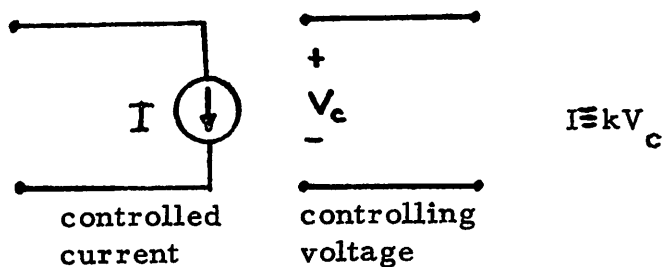


CANINE model:

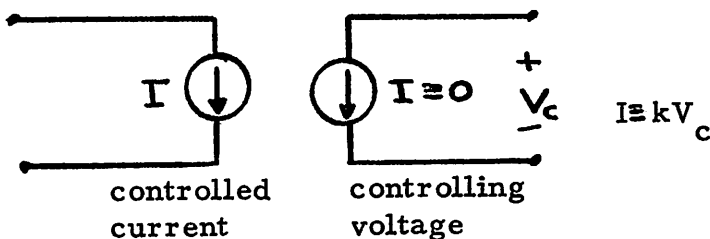


Voltage Controlled Current Source:

Ideal model:

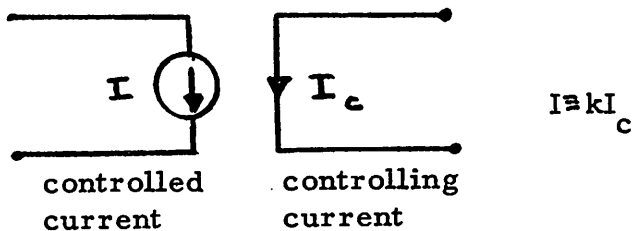


CANINE model:

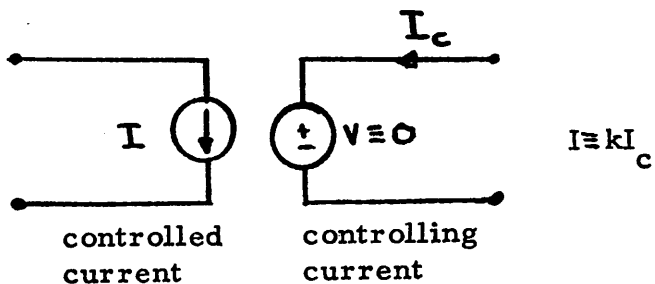


Current Controlled Current Source:

Ideal model:



CANINE model:



Thus we see that in all cases the controlling current is taken to be the current through a zero-valued voltage source, and the controlling voltage is taken to be the voltage across a zero-valued current source.

The coupling constants, denoted by k , are those that should be read in as corresponding elements of the VALUE array.

APPENDIX B

Data Cards for CANINE:

Notation:

I \Rightarrow Integer formatE \Rightarrow Exponential or floating point formatA \Rightarrow Alphanumeric formatcol \Rightarrow Column on data cardCard # 1:

Variables read in, in sequential order

NN, number of nodes (I)

NB, number of branches (I)

TSTART, starting time (E)

TEND, end time (E)

H, time increment (E)

NSTEP, number of time iterations per output (I)

NCONT, tree and \bar{F} output control (I)NCONT = 1 \Rightarrow outputs desiredNCONT = 0 \Rightarrow outputs not desired

col 1 - 5, - NN	}	DATA CARD # 1
col 6 - 10, - NB		
col 11 - 25, - TSTART		
col 26 - 40, - TEND		
col 41 - 55, - H		
col 56 - 60, - NSTEP		
col 80, - NCONT		

Card # 2:

Variables read in, in sequential order

NGRAPH, number of graphical outputs (I)

NALLOUT, control variable for use of ALLOUT subroutine (I)

NALLOUT = 1 \Rightarrow use of ALLOUT is desired

NALLOUT = 0 \Rightarrow use of ALLOUT is not desired

JOUT, number of outputs desired (I). To be used in conjunction with subroutine READOUT.

SCALE, scale factor (E)

eg. scale factor of 10^3 sets current unit to milliamps.

NSCALE, control variable for use of internal, automatic current scaling.

NSCALE = 1, \Rightarrow use scale factor read in as SCALE

NSCALE \neq 1, \Rightarrow use internal, automatic current scaling algorithm

col	1 - 5,	- NGRAPH	}	DATA CARD # 2
col	6 - 10,	- NALLOUT		
col	11 - 15,	- JOUT		
col	16 - 30,	- SCALE		
col	40,	- NSCALE		

Network Description Data Cards:

For each network branch, the following card (or set of cards) is needed. The order in which network branches are read in is arbitrary.

Variables read in, in sequential order

TYPE, Branch type (A)

E - independent voltage source

V - controlled voltage source

C - capacitance

L - inductance

R - resistance

I - controlled current source

J - independent current source

IBRAN, Branch number (I)

SORTYPE, Independent source type (A)

C - constant source

E - exponential source

P - periodic source

S - sinusoidal source

T - time-varying

CONTYPE, dependent source controlling type (A)

V - voltage controlled

I - current controlled

KONBRAN, dependent source controlling branch (I)

LEAV, node which branch leaves (I)

LENT, node which branch enters (I)

NCARDS, a flag signaling that more data pertaining to this branch
needs to be read in (independent sources only). (I)

NCARDS = 0 \Rightarrow no more data needed

NCARDS \neq 0 \Rightarrow more data needed

VALUE, value of branch element (E)

- Resistances in ohms
- Inductances in henrys
- Capacitances in farads
- Dependent source coupling constants in ohms, mhos, or
unitless (see Appendix A)

COND, for inductances, the initial current

for capacitances, the initial voltage

for constant independent sources, the source value (in volts
or amperes). (E)

col 1 - TYPE

col 2 - 4, - IBRAN

col 5 - SORTYPE

col 6 - CONTYPE

col 7 - 9, - KONBRAN

col 11 - 12, - LEAV

col 14 - 15, - LENT

col 17 - 18, - NCARDS

col 21 - 35, - VALUE

col 36 - 50, - COND

DATA CARD FOLLOWED BY
OTHER RELATED CARDS IF
NCARDS \neq 0

If NCARDS \neq 0, we need the following card (s), to describe
the corresponding nonconstant independent source.

If SORTYPE = S, ie a sinusoidal source, the signal is assumed
to be of the form

$$A \cdot \sin (w * t - \phi)$$

one card is required to describe the above

col 1 - 10, signal amplitude A, in volts or amperes (E)

col 11 - 20, signal frequency w, in radians/sec (E)

col 21 - 30, signal phase ϕ , at initial time (TSTART), (E)

If SORTYPE = E, ie an exponential source, the signal is assumed to be of the form

$$A e^{\gamma(t - \phi)}$$

one card is required to describe the above

col 1 - 10, signal amplitude, in volts or amperes (E)

col 11 - 20, time constant γ (sec^{-1}), (E)

col 21 - 30, signal phase ϕ , at $t = \text{TSTART}$. (E)

If SORTYPE = T or P, ie a time varying or periodic source, we need the following set of cards.

- a) card # 1, col 1-5, number of time points (I)
- b) as many cards as needed to specify the source values at the time points, allowing for 8 source values/data card, each being allotted 10 columns of space (E).
- c) as many cards as needed to specify the time points, allowing for 8 time points /data card, each being allotted 10 columns of space (E).

OUTPUT specifications:

Only one type of output is allowed for any one network analysis, ie, only one of NGRAPH, NALLOUT and JOUT can be nonzero.

The following data cards follow immediately after the network description data cards.

IF NGRAPH \neq 0, we need NGRAPH (\leq 5) data cards with the following information

col 1 - 5, branch number (I)

col 10, output type desired (I)

1 \Rightarrow current desired

0 \Rightarrow voltage desired

If JOUT \neq 0, we need JOUT (\leq 200) data cards with the following information

col 1 - 5, branch number (I)

col 10, output type desired (I)

1 \Rightarrow current desired

0 \Rightarrow voltage desired

If NALLOUT \neq 0, no other data cards are required.

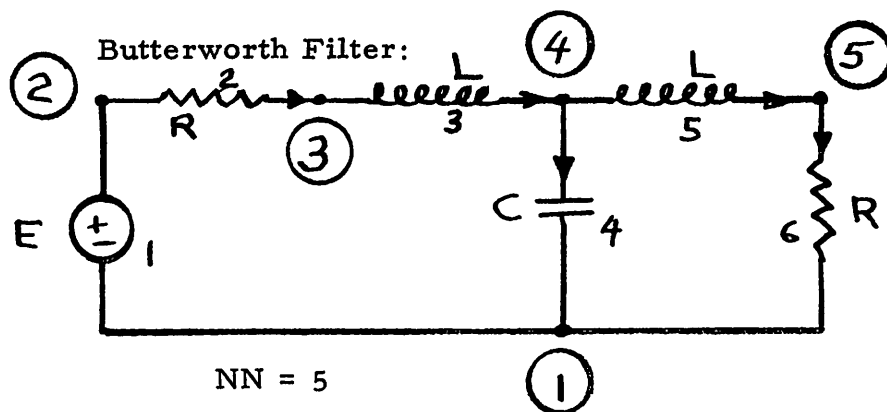
Note that when one or more networks are analyzed in one batch, the last data card of the batch should be a blank card.

APPENDIX C

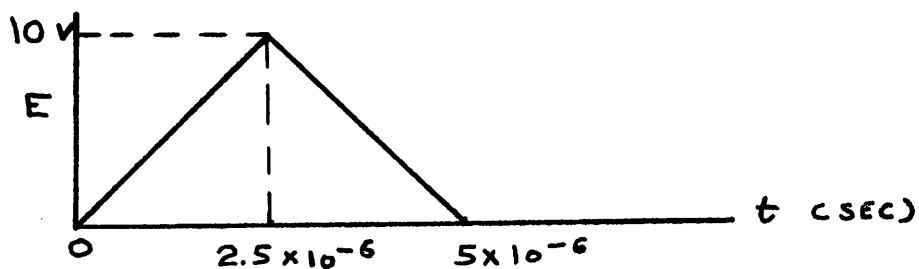
Sample Problems:

Notation:

- Circled numbers indicate node numbers
- Uncircled numbers indicate branch numbers
- R's indicate resistances, in ohms
- L's indicate inductances, in henrys
- C's indicate capacitances, in farads
- NN is the number of nodes
- NB is the number of branches
- H is the integration time step, in seconds
- TSTART is the starting time, in seconds
- TEND is the final time, in seconds

Sample Problem # 1:

The input E is specified to be

Specifications:

- Initial time = 0 (TSTART = 0.0)
- Final time = 10^{-4} (TEND = 0.0001)
- Time increment = 2×10^{-6} (H = 0.000002)
- Desire results, at each time point, to be outputed (NSTEP = 1)
- Desire tree and \tilde{F} to be outputed (NCONT = 1)
- Desire current to be in millamps (SCALE = 10^3 and NSCALE = 1)
- Desire the following graphical outputs

Branch 1 voltage	}	(NGRAPH = 3)
Branch 2 current		
Branch 6 voltage		

Specify zero initial conditions

The required data cards, for this problem, may be seen on the following page.

The central processor time, for this problem, was 2.86 seconds.

Comments on Sample Problem # 1:

The proper tree selected at the initial time point coincides with the optimal tree picked at the second time point. Thus \bar{F} is computed only once and hence, is outputted only once.

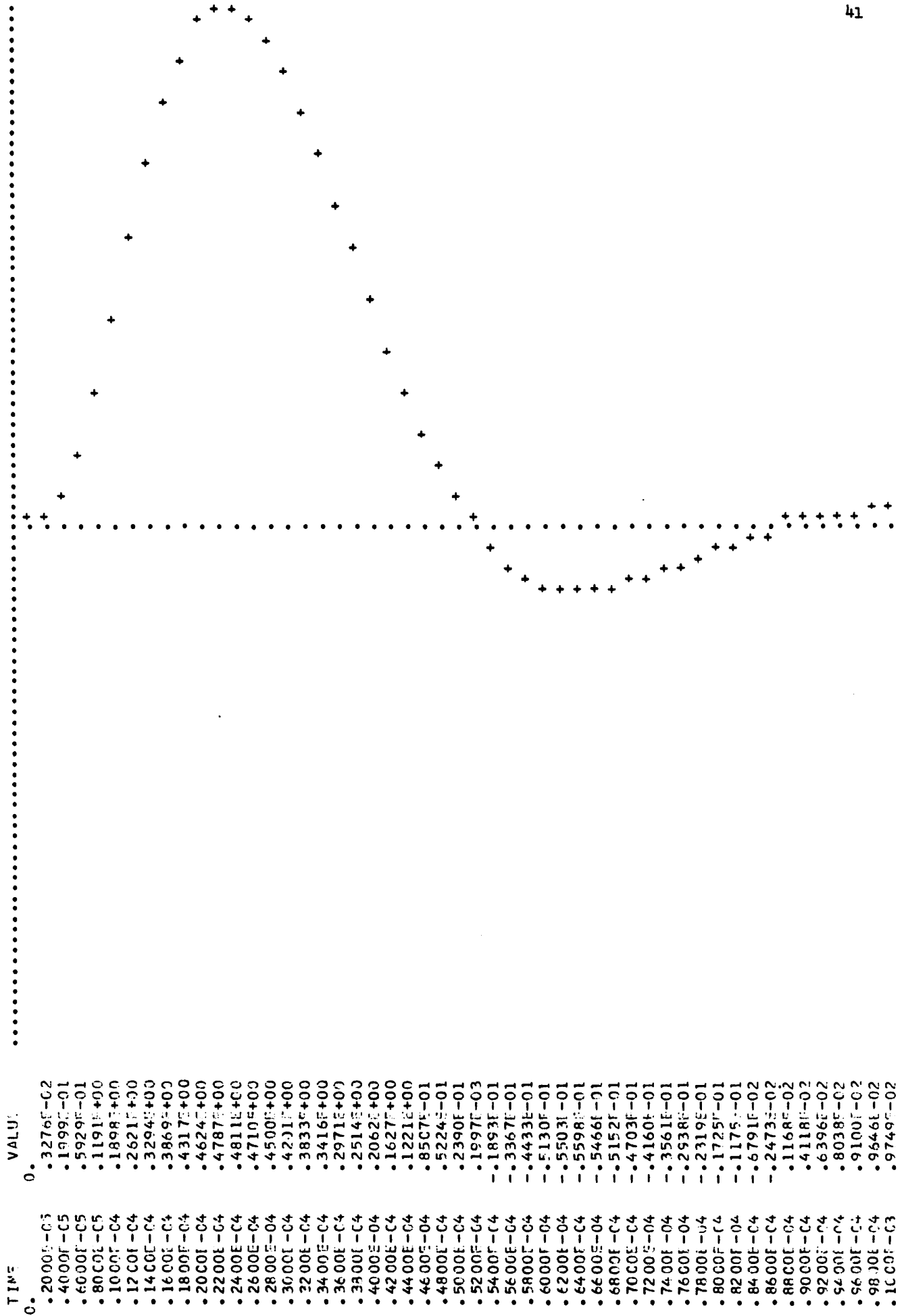
BRANCH 1 VOLTAGE

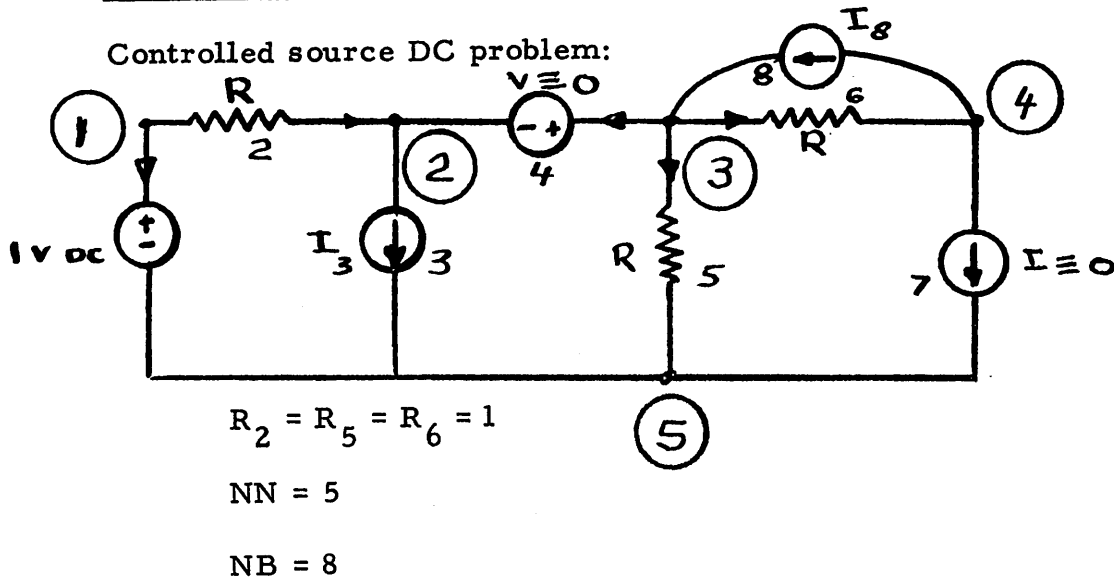
TIME	VALUE
0.	0.
.2000E-05	.4000E+01
.4000E-05	.4000E+01
.6000E-05	0.
.8000E-05	0.
.1000E-04	0.
.1200E-04	0.
.1400E-04	0.
.1600E-04	0.
.1800E-04	0.
.2000E-04	0.
.2200E-04	0.
.2400E-04	0.
.2600E-04	0.
.2800E-04	0.
.3000E-04	0.
.3200E-04	0.
.3400E-04	0.
.3600E-04	0.
.3800E-04	0.
.4000E-04	0.
.4200E-04	0.
.4400E-04	0.
.4600E-04	0.
.4800E-04	0.
.5000E-04	0.
.5200E-04	0.
.5400E-04	0.
.5600E-04	0.
.5800E-04	0.
.6000E-04	0.
.6200E-04	0.
.6400E-04	0.
.6600E-04	0.
.6800E-04	0.
.7000E-04	0.
.7200E-04	0.
.7400E-04	0.
.7600E-04	0.
.7800E-04	0.
.8000E-04	0.
.8200E-04	0.
.8400E-04	0.
.8600E-04	0.
.8800E-04	0.
.9000E-04	0.
.9200E-04	0.
.9400E-04	0.
.9600E-04	0.
.9800E-04	0.
.1000E-03	0.

BRANCH 2 CURRENT

TIME	VALU.
2000E-05	.7240E-03
4000E-05	.1466E-02
6000E-05	.1684E-02
8000E-05	.1307E-02
1000E-04	.9771E-03
1200E-04	.6925E-03
1400E-04	.4517E-03
1600E-04	.2522E-03
1800E-04	.9122E-04
2000E-04	-.3454E-04
2200E-04	-.1286E-03
2400E-04	-.1947E-03
2600E-04	-.2357E-03
2800E-04	-.2583E-03
3000E-04	-.2633E-03
3200E-04	-.2550E-03
3400E-04	-.2366E-03
3600E-04	-.2112E-03
3800E-04	-.1811E-03
4000E-04	-.1487E-03
4200E-04	-.1157E-03
4400E-04	-.8358E-04
4600E-04	-.5357E-04
4800E-04	-.2646E-04
5000E-04	-.2818E-05
5200E-04	.1705E-04
5400E-04	.3304E-04
5600E-04	.4522E-04
5800E-04	.5378E-04
6000E-04	.5903E-04
6200E-04	.6135E-04
6400E-04	.6116E-04
6600E-04	.5989E-04
6800E-04	.5499E-04
7000E-04	.4987E-04
7200E-04	.4392E-04
7400E-04	.3751E-04
7600E-04	.3094E-04
7800E-04	.2446E-04
8000E-04	.1829E-04
8200E-04	.1250E-04
8400E-04	.7487E-05
8600E-04	.3042E-05
8800E-04	-.7020E-06
9000E-04	-.3737E-05
9200E-04	-.6084E-05
9400E-04	-.7783E-05
9600E-04	-.8491E-05
9800E-04	-.9475E-05
1000E-03	-.9509E-05

BRANCH 6 VOLTAGE



Sample Problem # 2:

Branch 3 is a current controlled current source, controlled by branch 4

$$I_3 = 5 * I_4$$

Branch 8 is a voltage controlled current source, controlled by branch 7

$$I_8 = 3 * V_7$$

Specifications:

- Since our problem is a resistive DC network, we need the solution at only one time point. Set $TSTART = 0.0 = TEND$
- The time increments is arbitrary (set $H = 0.0$)
- Desire results at each time point to be outputed ($NSTEP = 1$)
- Do not desire tree and \bar{F} to be outputed ($NCONT = 0$)
- Desire current to be in amperes. ($SCALE = 1.0$ and $NSCALE = 1$)

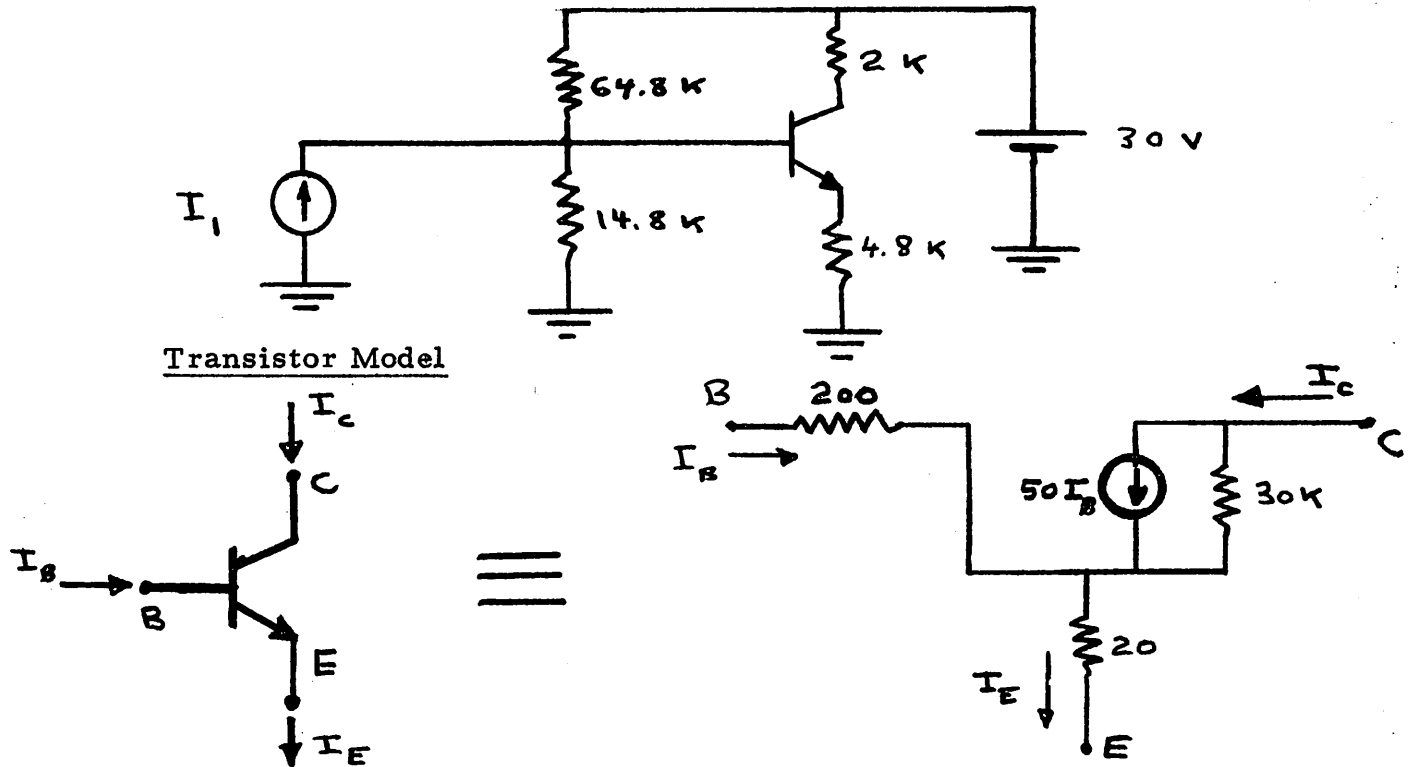
— Desire all voltages and currents outputed (JOUT = 16)

The required data cards, for this problem, may be seen on the following page. The central processor time, for this problem, was 0.234 seconds.

TIME =	V.		
BRANCH	1	CURRENT	-.13333E+01
BRANCH	1	VOLTAGE	.10000E+01
BRANCH	2	CURRENT	.13333E+01
BRANCH	2	VOLTAGE	.13333E+01
BRANCH	3	CURRENT	.16667E+01
BRANCH	3	VOLTAGE	-.33333E+00
BRANCH	4	CURRENT	.33333E+00
BRANCH	4	VOLTAGE	0.
BRANCH	5	CURRENT	-.33333E+00
BRANCH	5	VOLTAGE	-.33333E+00
BRANCH	6	CURRENT	-.25000E+00
BRANCH	6	VOLTAGE	-.25000E+00
BRANCH	7	CURRENT	0.
BRANCH	7	VOLTAGE	-.83333E-01
BRANCH	8	CURRENT	-.25000E+00
BRANCH	8	VOLTAGE	.25000E+00

Sample Problem # 3:

D. C. Amplifier

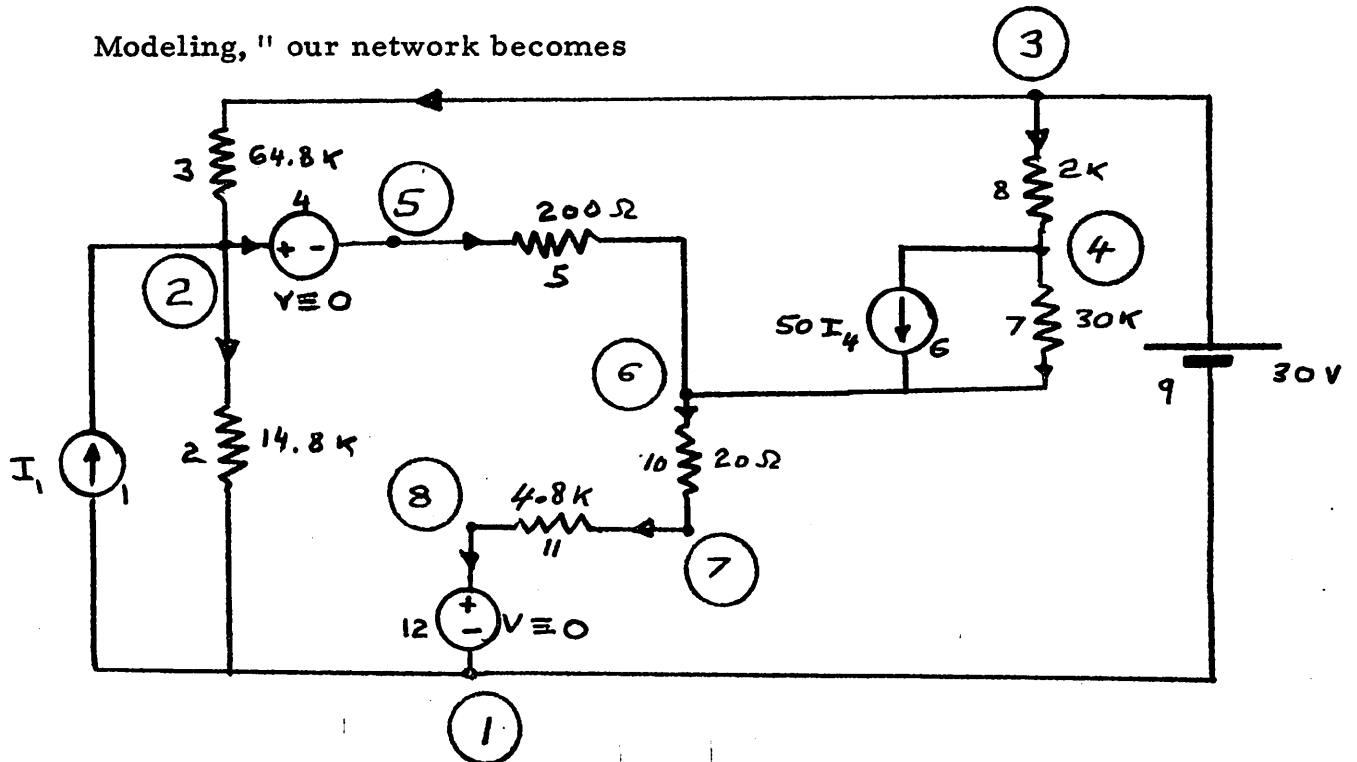


Transistor Model

The output will be the emitter current, and will be taken to be

a current through a zero valved voltage source. Modeling the controlled source in the way described in the section on "Dependent Source

Modeling," our network becomes



The approximate theoretical gain (neglecting the 30 K across the controlled current source) can be shown to be:

$$\frac{\Delta I_{12}}{\Delta I_1} \cong 2.4$$

about a quiescent value of I_{12} of 1.1 ma.

Specifications:

$$I_1 = A \sin (1.8 t)$$

$$A = 0.1 \text{ milliamps}$$

t is in seconds

- initial time = 0 (TSTART = 0.0)
- final time = 5 (TEND = 5.0)
- time increment = 0.1 (H = 0.1)
- desire results, at each time point, to be outputed (NSTEP = 1)
- desire tree and F to be outputed (NCONT = 1)
- desire internal, automatic current scaling (NSCALE \neq 1)
- desire the following graphical outputs

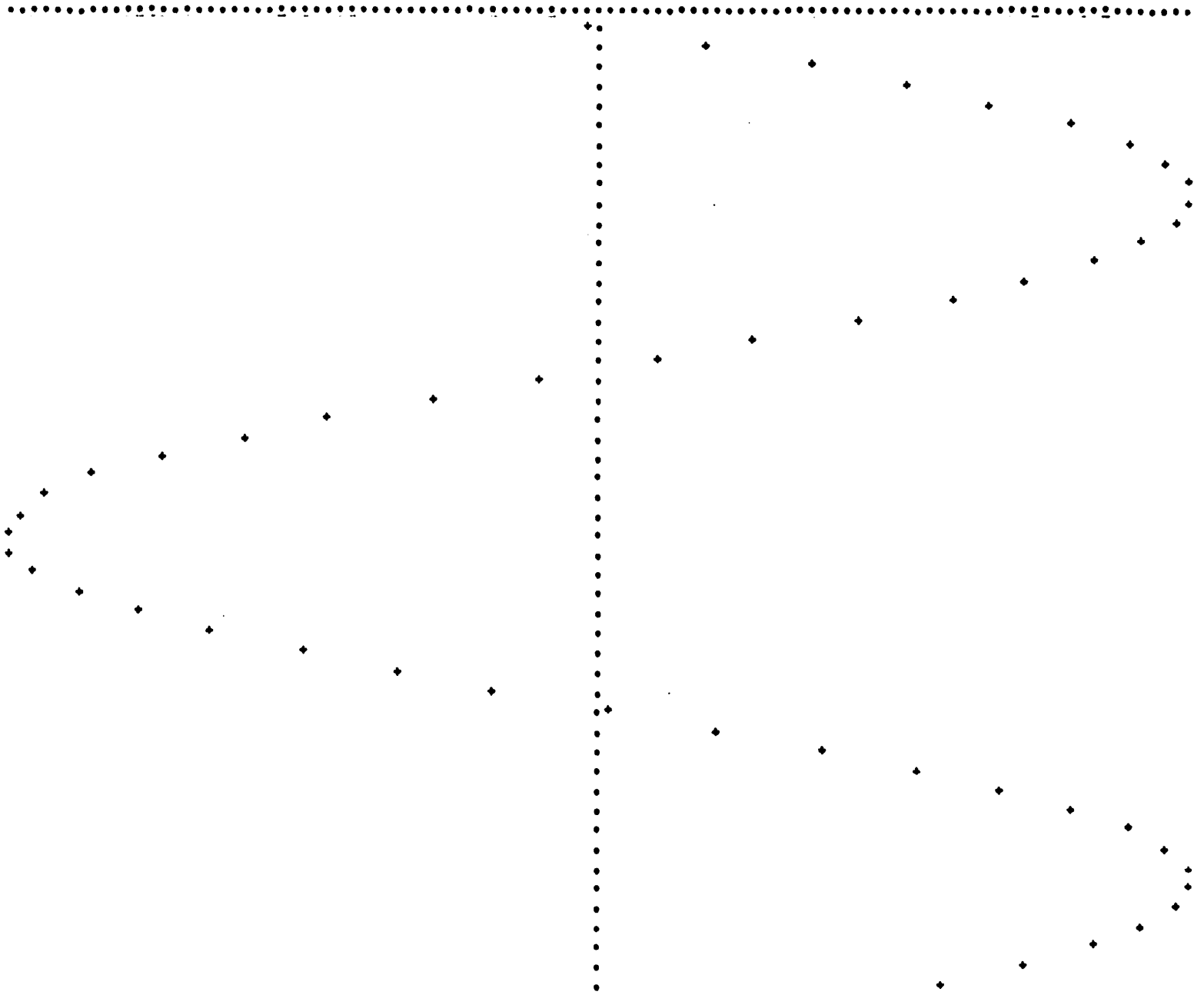
Branch 1 current	}	(NGRAPH = 4)
Branch 4 current		
Branch 12 current		
Branch 6 current		

The required data cards, for this problem, may be seen on the following page.

The central processor time, for this problem, was 8.48 seconds.

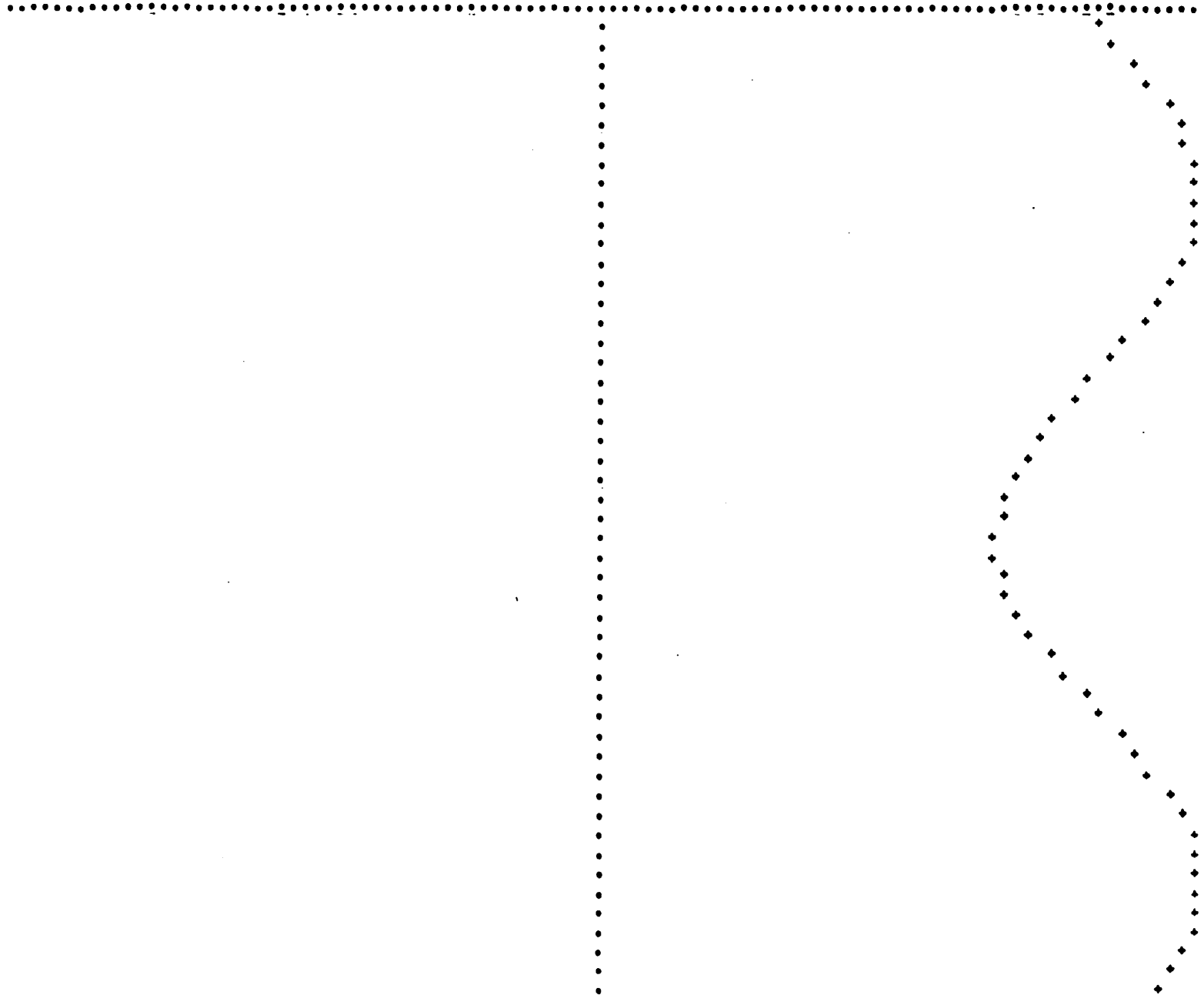
BRANCH 1 CURRENT

TIME	VALUE
0.	-.9002E-18
.1000E+00	.1790E-04
.2000E+00	.3523E-04
.3000E+00	.5141E-04
.4000E+00	.6594E-04
.5000E+00	.7833E-04
.6000E+00	.8820E-04
.7000E+00	.9521E-04
.8000E+00	.9915E-04
.9000E+00	.9988E-04
.1000E+01	.9738E-04
.1100E+01	.9174E-04
.1200E+01	.8314E-04
.1300E+01	.7185E-04
.1400E+01	.5823E-04
.1500E+01	.4274E-04
.1600E+01	.2586E-04
.1700E+01	.8150E-05
.1800E+01	-.9825E-05
.1900E+01	-.2748E-04
.2000E+01	-.4425E-04
.2100E+01	-.5959E-04
.2200E+01	-.7301E-04
.2300E+01	-.8406E-04
.2400E+01	-.9240E-04
.2500E+01	-.9775E-04
.2600E+01	-.9995E-04
.2700E+01	-.9891E-04
.2800E+01	-.9468E-04
.2900E+01	-.8739E-04
.3000E+01	-.7728E-04
.3100E+01	-.6467E-04
.3200E+01	-.4996E-04
.3300E+01	-.3365E-04
.3400E+01	-.1625E-04
.3500E+01	.1681E-05
.3600E+01	.1955E-04
.3700E+01	.3680E-04
.3800E+01	.5285E-04
.3900E+01	.6719E-04
.4000E+01	.7937E-04
.4100E+01	.8898E-04
.4200E+01	.9571E-04
.4300E+01	.9935E-04
.4400E+01	.9978E-04
.4500E+01	.9699E-04
.4600E+01	.9106E-04
.4700E+01	.8219E-04
.4800E+01	.7067E-04
.4900E+01	.5686E-04



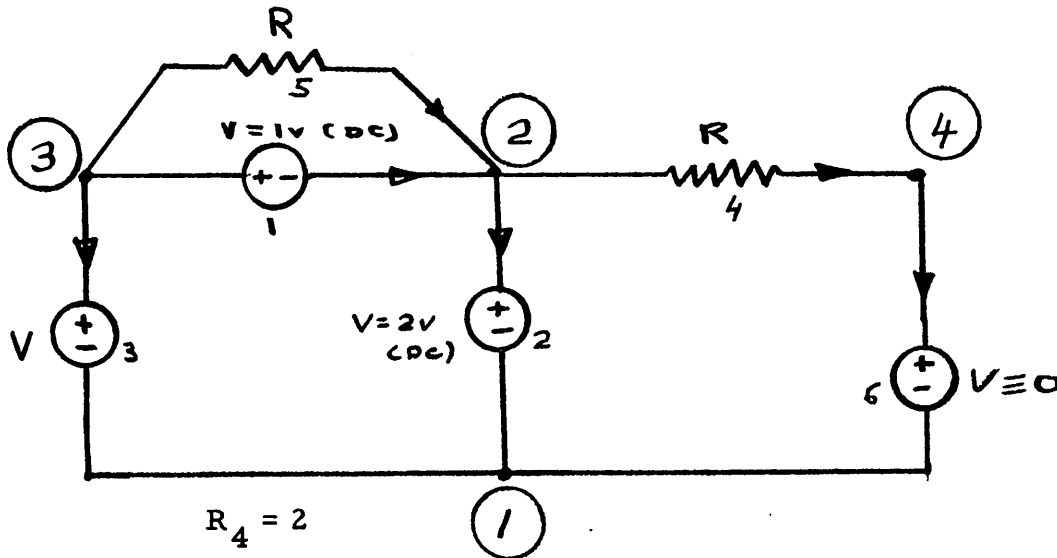
BRANCH 12 CURRENT

TIME	VALUE
.1000E+00	.1138E-02
.2000E+00	.1180E-02
.3000E+00	.1221E-02
.4000E+00	.1259E-02
.5000E+00	.1293E-02
.6000E+00	.1322E-02
.7000E+00	.1345E-02
.8000E+00	.1362E-02
.9000E+00	.1371E-02
.1000E+01	.1373E-02
.1100E+01	.1367E-02
.1200E+01	.1354E-02
.1300E+01	.1333E-02
.1400E+01	.1307E-02
.1500E+01	.1275E-02
.1600E+01	.1238E-02
.1700E+01	.1198E-02
.1800E+01	.1157E-02
.1900E+01	.1114E-02
.2000E+01	.1073E-02
.2100E+01	.1033E-02
.2200E+01	.9971E-03
.2300E+01	.9655E-03
.2400E+01	.9395E-03
.2500E+01	.9199E-03
.2600E+01	.9072E-03
.2700E+01	.9021E-03
.2800E+01	.9045E-03
.2900E+01	.9145E-03
.3000E+01	.9317E-03
.3100E+01	.9555E-03
.3200E+01	.9852E-03
.3300E+01	.1020E-02
.3400E+01	.1058E-02
.3500E+01	.1099E-02
.3600E+01	.1141E-02
.3700E+01	.1184E-02
.3800E+01	.1224E-02
.3900E+01	.1262E-02
.4000E+01	.1296E-02
.4100E+01	.1324E-02
.4200E+01	.1347E-02
.4300E+01	.1363E-02
.4400E+01	.1372E-02
.4500E+01	.1373E-02
.4600E+01	.1366E-02
.4700E+01	.1352E-02
.4800E+01	.1331E-02
.4900E+01	.1304E-02
.4900E+01	.1271E-02



Sample Problem # 4:

Compatible voltage source loop



$$R_4 = 2$$

$$R_5 = 1$$

$$NN = 4$$

$$NB = 6$$

Branch 3 is a current controlled voltage source, controlled by branch 6

$$V_3 = 3 * I_6$$

Specifications:

- since we have a resistive DC problem, we need solution at only one time point.
- the time increment is arbitrary, ($H = 0.0$)
- desire results, at each time point, to be outputted. ($NSTEP = 1$)
- do not desire tree and \underline{F} , to be outputted ($NCONT = 0$)

- desire automatic internal scaling (NSCALE \neq 1)
- desire all branch currents and voltages to be outputed.

The required data cards, for this problem, may be seen on the following page.

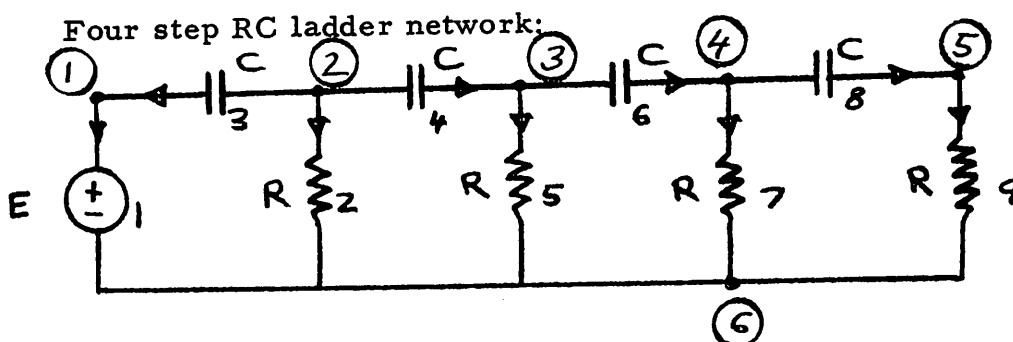
The central processor time, for this problem, was 0.23 seconds.

Comments on Sample Problem # 4:

Note that when dependent and independent voltage source loops exist in a network, it is of paramount importance for them to be "compatible," that Kirchhoff's voltage law be satisfied around that loop.

Incompatible loops, of the above type, will yield incorrect executions of CANINE. The same holds for cutsets of independent and dependent current sources.

TIME =	0.		
BRANCH	1	CURRENT	-.10000E+01
BRANCH	2	CURRENT	-.10000E+01
BRANCH	3	CURRENT	.24136-225
BRANCH	4	CURRENT	.10000E+01
BRANCH	5	CURRENT	.10000E+01
BRANCH	6	CURRENT	.10000E+01
BRANCH	1	VOLTAGE	.10000E+01
BRANCH	2	VOLTAGE	.20000E+01
BRANCH	3	VOLTAGE	.30000E+01
BRANCH	4	VOLTAGE	.20000E+01
BRANCH	5	VOLTAGE	.10000E+01
BRANCH	6	VOLTAGE	0.

Sample Problem # 5:

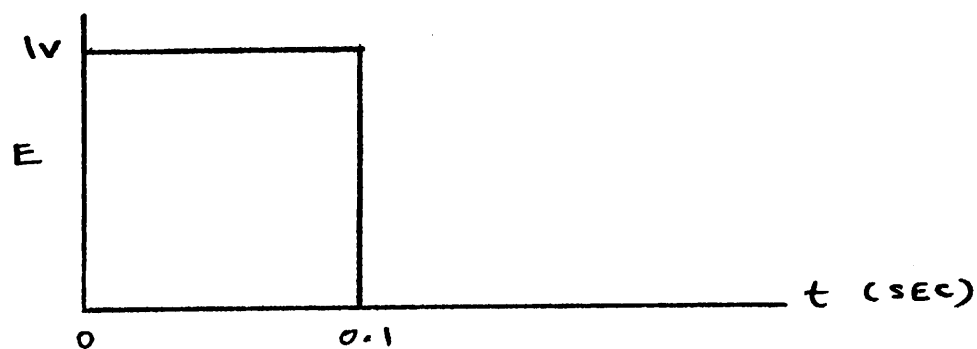
$$R = 10^3$$

$$C = 10^{-5}$$

$$NN = 6$$

$$NB = 9$$

The input E is specified as follows:



Specifications:

- initial time = 0 (TSTART = 0.0)
- final time = 50 milliseconds (TEND = 0.05)
- time increment = 1 millisecond (H = 0.001)
- desire results at each time point to be outputted (NSTEP = 1)
- do not desire tree information and F to be outputted (NCONT = 0)

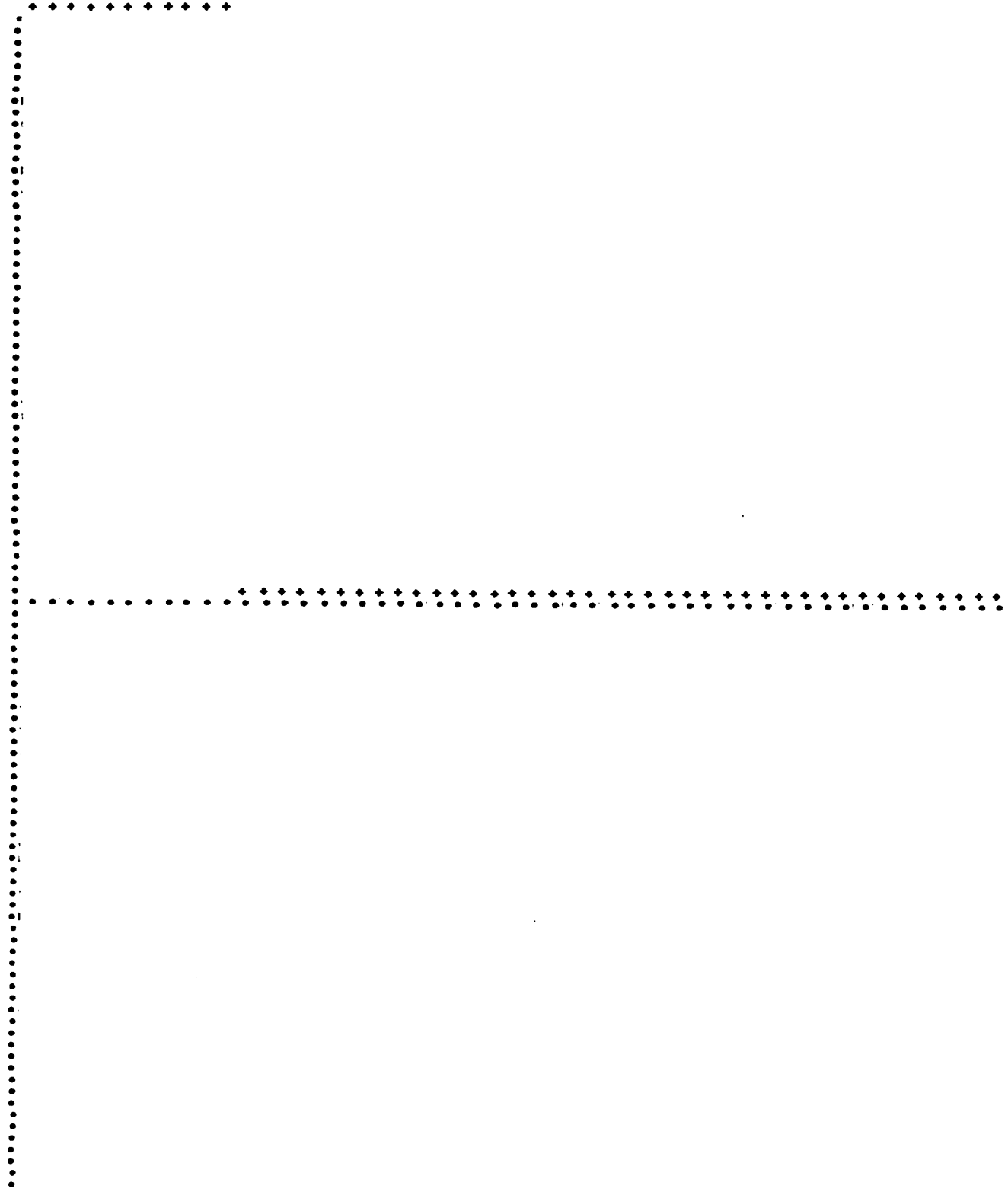
- desire internal automatic current scaling (NSCALE # 1)
- zero initial conditions
- desire the following graphical outputs

Branch 1 voltage } (NGRAPH = 2)
Branch 5 voltage }

The required data cards for this problem may be seen on the following page. The central processor time, for this problem, was 4.17 seconds.

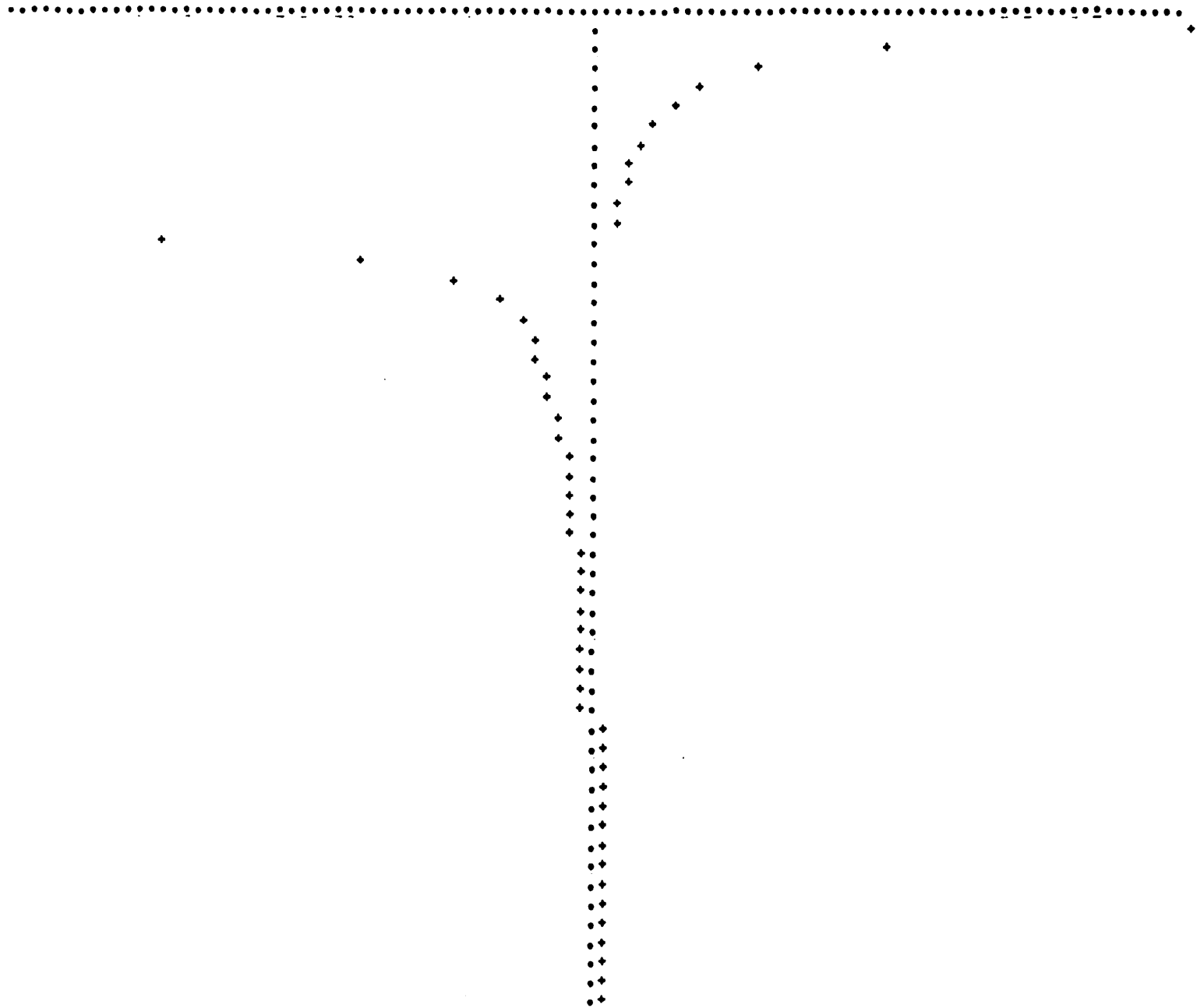
BRANCH 1 VOLTAGE

TIME	VALUE
0.	.1000E+01
.1000E-02	.1000E+01
.2000E-02	.1000E+01
.3000E-02	.1000E+01
.4000E-02	.1000E+01
.5000E-02	.1000E+01
.6000E-02	.1000E+01
.7000E-02	.1000E+01
.8000E-02	.1000E+01
.9000E-02	.1000E+01
.1000E-01	.1000E+01
.1100E-01	0.
.1200E-01	0.
.1300E-01	0.
.1400E-01	0.
.1500E-01	0.
.1600E-01	0.
.1700E-01	0.
.1800E-01	0.
.1900E-01	0.
.2000E-01	0.
.2100E-01	0.
.2200E-01	0.
.2300E-01	0.
.2400E-01	0.
.2500E-01	0.
.2600E-01	0.
.2700E-01	0.
.2800E-01	0.
.2900E-01	0.
.3000E-01	0.
.3100E-01	0.
.3200E-01	0.
.3300E-01	0.
.3400E-01	0.
.3500E-01	0.
.3600E-01	0.
.3700E-01	0.
.3800E-01	0.
.3900E-01	0.
.4000E-01	0.
.4100E-01	0.
.4200E-01	0.
.4300E-01	0.
.4400E-01	0.
.4500E-01	0.
.4600E-01	0.
.4700E-01	0.
.4800E-01	0.
.4900E-01	0.
.5000E-01	0.



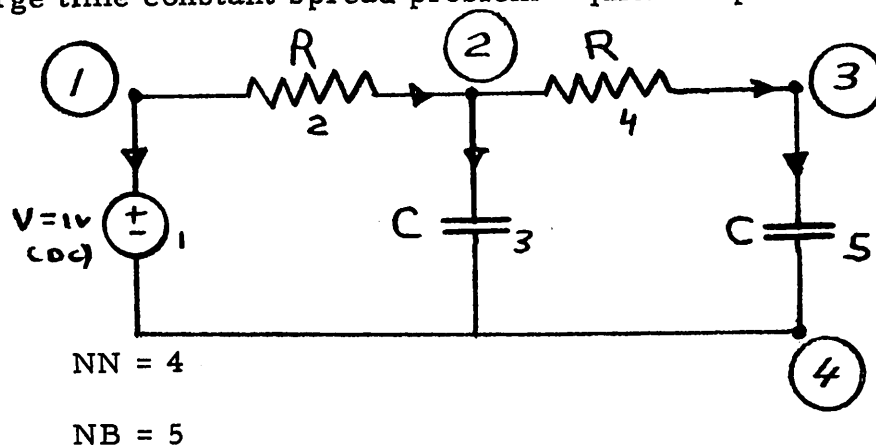
BRANCH 5 VOLTAGE

TIME	VALUE
0.	.1000E+01
.1000E-02	.4983E+00
.2000E-02	.2778E+00
.3000E-02	.1750E+00
.4000E-02	.1222E+00
.5000E-02	.9125E-01
.6000E-02	.7032E-01
.7000E-02	.5446E-01
.8000E-02	.4151E-01
.9000E-02	.3051E-01
.1000E-01	.2098E-01
.1100E-01	-.7365E+00
.1200E-01	-.3827E+00
.1300E-01	-.2274E+00
.1400E-01	-.1552E+00
.1500E-01	-.1182E+00
.1600E-01	-.9647E-01
.1700E-01	-.8171E-01
.1800E-01	-.7043E-01
.1900E-01	-.6113E-01
.2000E-01	-.5312E-01
.2100E-01	-.4609E-01
.2200E-01	-.3985E-01
.2300E-01	-.3428E-01
.2400E-01	-.2932E-01
.2500E-01	-.2489E-01
.2600E-01	-.2094E-01
.2700E-01	-.1742E-01
.2800E-01	-.1428E-01
.2900E-01	-.1150E-01
.3000E-01	-.9026E-02
.3100E-01	-.6835E-02
.3200E-01	-.4898E-02
.3300E-01	-.3188E-02
.3400E-01	-.1682E-02
.3500E-01	-.3601E-03
.3600E-01	.7974E-03
.3700E-01	.1807E-02
.3800E-01	.2685E-02
.3900E-01	.3444E-02
.4000E-01	.4098E-02
.4100E-01	.4656E-02
.4200E-01	.5131E-02
.4300E-01	.5529E-02
.4400E-01	.5861E-02
.4500E-01	.6133E-02
.4600E-01	.6351E-02
.4700E-01	.6523E-02
.4800E-01	.6653E-02
.4900E-01	.6745E-02
.5000E-01	.6806E-02



Sample Problem # 6:

Large time constant spread problem - quick response:



We desire the step response associated with the small time constant.

Specifications:

- initial time = 0 (TSTART = 0.0)
- final time = 50 microsec. (TEND = 5×10^{-5})
- time increment = 1 microsec. ($H = 10^{-6}$)
- desire results, at each time point, to be outputted (NSTEP = 1)
- do not desire tree and F to be outputted (NCONT \neq 1)
- desire internal automatic current scaling (NSCALE \neq 1)
- zero initial conditions
- desire the following graphical outputs

Branch 3 voltage	}	(NGRAPH = 4)
Branch 4 current		
Branch 2 current		
Branch 5 voltage		

The data cards, for this problem, may be seen on the following page.

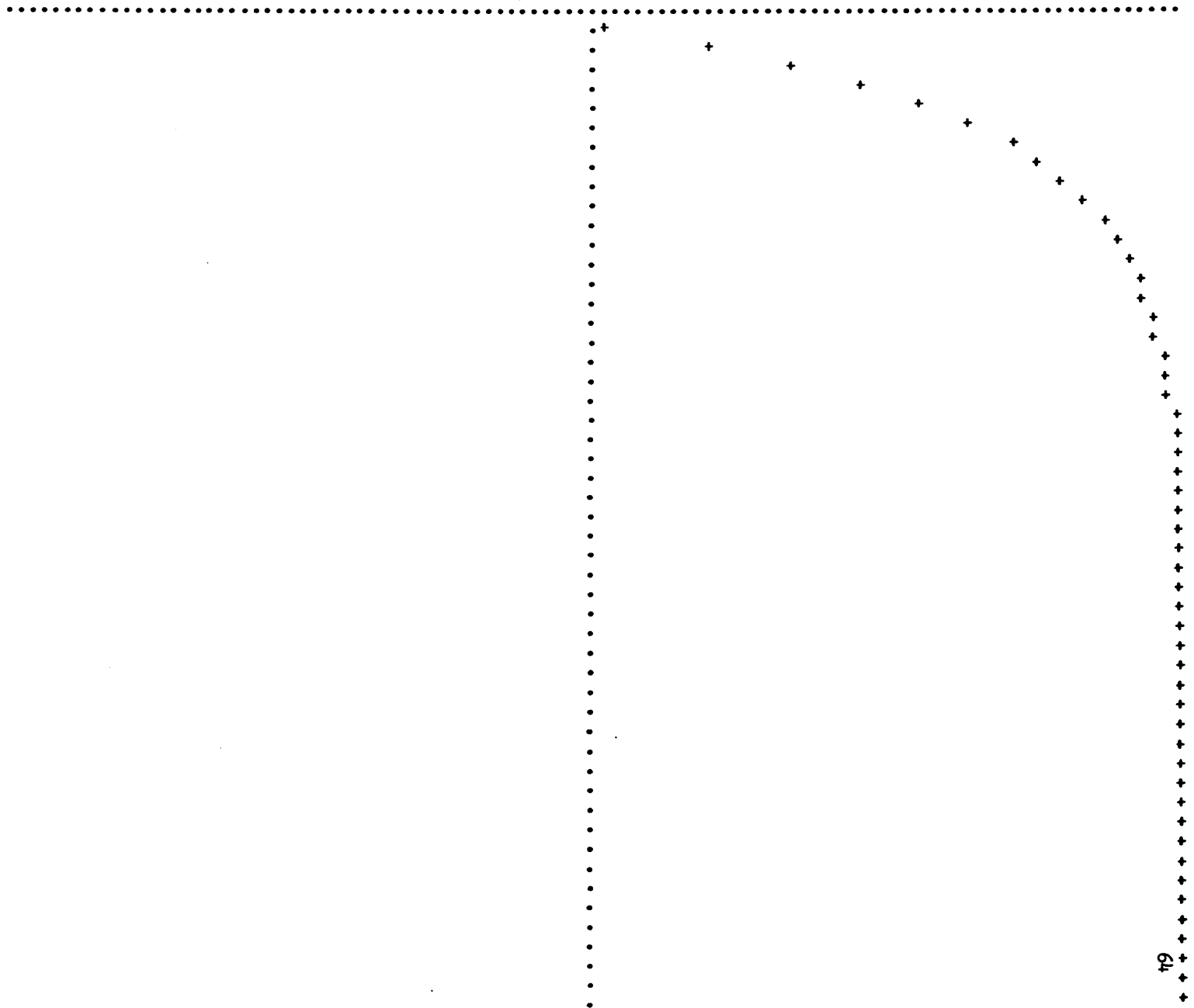
The central processor, time for this problem, was 2.96 seconds.

Comments on Sample Problem # 6:

The quick response steady state voltage across (3 is 0.5 volts, and, as will be noted in problem # 7, this value must be used as the initial conditions on C_3 when the slow time response is desired.

BRANCH 3 VOLTAGE

TIME	VALUE
0.	0.
.1000E-05	.9091E-01
.2000E-05	.1653E+00
.3000E-05	.2261E+00
.4000E-05	.2759E+00
.5000E-05	.3157E+00
.6000E-05	.3500E+00
.7000E-05	.3773E+00
.8000E-05	.3996E+00
.9000E-05	.4178E+00
.1000E-04	.4328E+00
.1100E-04	.4450E+00
.1200E-04	.4550E+00
.1300E-04	.4632E+00
.1400E-04	.4699E+00
.1500E-04	.4754E+00
.1600E-04	.4798E+00
.1700E-04	.4835E+00
.1800E-04	.4865E+00
.1900E-04	.4890E+00
.2000E-04	.4910E+00
.2100E-04	.4926E+00
.2200E-04	.4940E+00
.2300E-04	.4951E+00
.2400E-04	.4960E+00
.2500E-04	.4967E+00
.2600E-04	.4973E+00
.2700E-04	.4978E+00
.2800E-04	.4982E+00
.2900E-04	.4985E+00
.3000E-04	.4988E+00
.3100E-04	.4990E+00
.3200E-04	.4992E+00
.3300E-04	.4993E+00
.3400E-04	.4995E+00
.3500E-04	.4996E+00
.3600E-04	.4996E+00
.3700E-04	.4997E+00
.3800E-04	.4998E+00
.3900E-04	.4998E+00
.4000E-04	.4998E+00
.4100E-04	.4999E+00
.4200E-04	.4999E+00
.4300E-04	.4999E+00
.4400E-04	.4999E+00
.4500E-04	.4999E+00
.4600E-04	.5000E+00
.4700E-04	.5000E+00
.4800E-04	.5000E+00
.4900E-04	.5000E+00
.5000E-04	.5000E+00



BRANCH 2 CURRENT

TIME	VALUE
• 1000E-C2	• 1000E-C2
• 1000E-C5	• 9091E-C3
• 2000E-C5	• 8347E-C3
• 3000E-C5	• 7739E-C3
• 4000E-C5	• 7241E-C3
• 5000E-C5	• 6833E-C3
• 6000E-C5	• 6500E-C3
• 7000E-C5	• 6227E-C3
• 8000E-C5	• 6004E-C3
• 9000E-C5	• 5822E-C3
• 1000E-C4	• 5672E-C3
• 1100E-C4	• 5550E-C3
• 1200E-C4	• 5450E-C3
• 1300E-C4	• 5368E-C3
• 1400E-C4	• 5301E-C3
• 1500E-C4	• 5244E-C3
• 1600E-C4	• 5202E-C3
• 1700E-C4	• 5165E-C3
• 1800E-C4	• 5135E-C3
• 1900E-C4	• 5110E-C3
• 2000E-C4	• 5090E-C3
• 2100E-C4	• 5074E-C3
• 2200E-C4	• 5060E-C3
• 2300E-C4	• 5049E-C3
• 2400E-C4	• 5040E-C3
• 2500E-C4	• 5033E-C3
• 2600E-C4	• 5027E-C3
• 2700E-C4	• 5022E-C3
• 2800E-C4	• 5018E-C3
• 2900E-C4	• 5015E-C3
• 3000E-C4	• 5012E-C3
• 3100E-C4	• 5010E-C3
• 3200E-C4	• 5008E-C3
• 3300E-C4	• 5007E-C3
• 3400E-C4	• 5005E-C3
• 3500E-C4	• 5004E-C3
• 3600E-C4	• 5004E-C3
• 3700E-C4	• 5003E-C3
• 3800E-C4	• 5002E-C3
• 3900E-C4	• 5002E-C3
• 4000E-C4	• 5002E-C3
• 4100E-C4	• 5001E-C3
• 4200E-C4	• 5001E-C3
• 4300E-C4	• 5001E-C3
• 4400E-C4	• 5001E-C3
• 4500E-C4	• 5001E-C3
• 4600E-C4	• 5000E-C3
• 4700E-C4	• 5000E-C3
• 4800E-C4	• 5000E-C3
• 4900E-C4	• 5000E-C3
• 5000E-C4	• 5000E-C3

Sample Problem # 7:

Large time constant spread problem. a slow response.

The network is identical to that of problem # 6. However, this time, we desire the step response associated with the large time constant.

Specifications:

- initial time = 0 (TSTART = 0.0)
- final time = 500 sec (TEND = 500.0)
- time increment = 10 sec. (H = 10.0)
- desire results, at each time point, to be outputed. (NSTEP = 1)
- do not desire tree information and F to be outputed (NCONT = 0)
- desire internal automatic current scaling. (NSCALE ≠ 1)
- initial voltages are

$$V_{c3}(0) = 0.5 \text{ v}$$

$$V_{c5}(0) = 0 \text{ v}$$

desire the following graphical outputs

Branch 3 voltage	}	(NGRAPH = 4)
Branch 4 current		
Branch 2 current		
Branch 5 voltage		

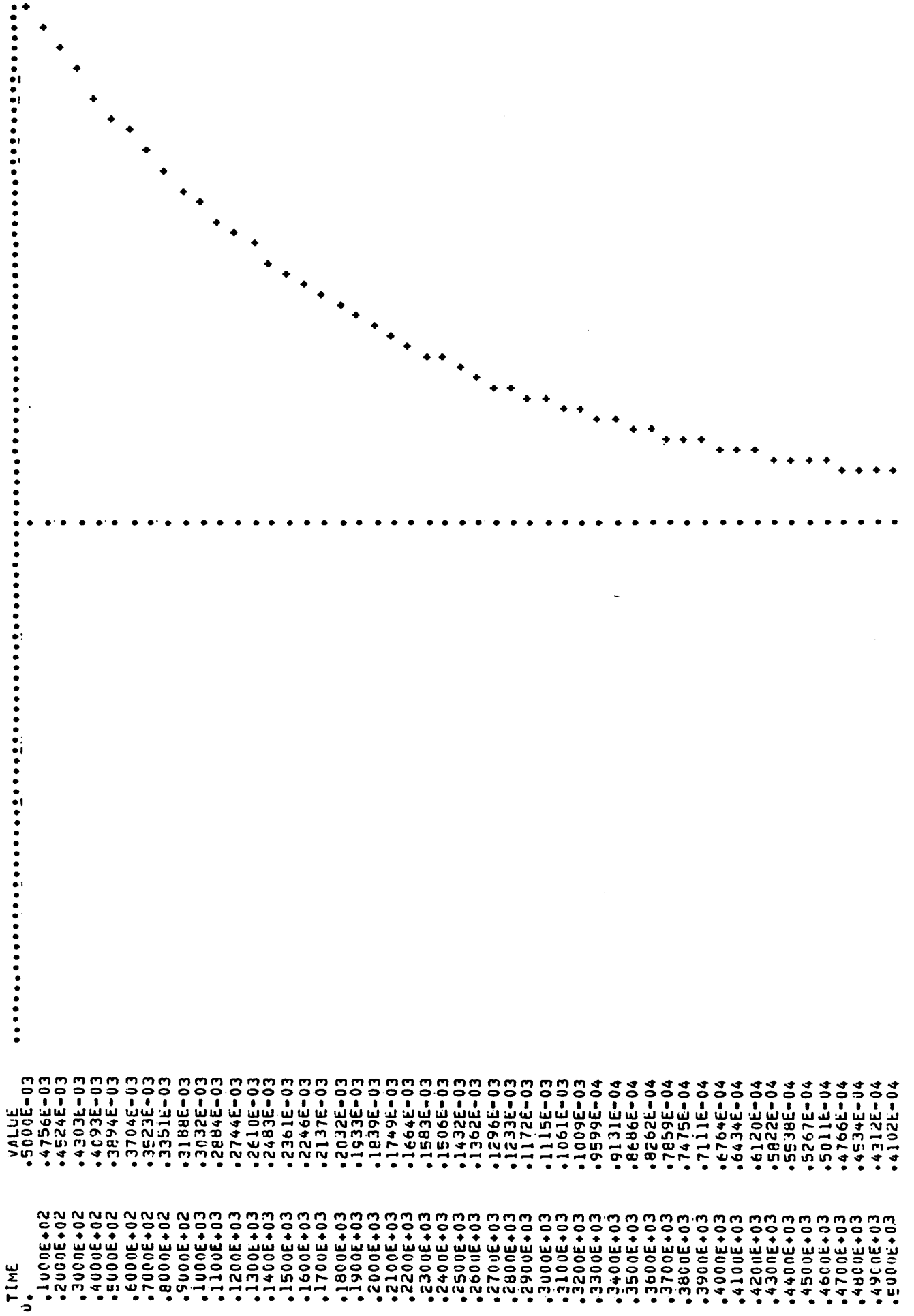
The data cards for this problem may be seen on the following page.

The central processor time, for this problem, was 3.06 seconds.

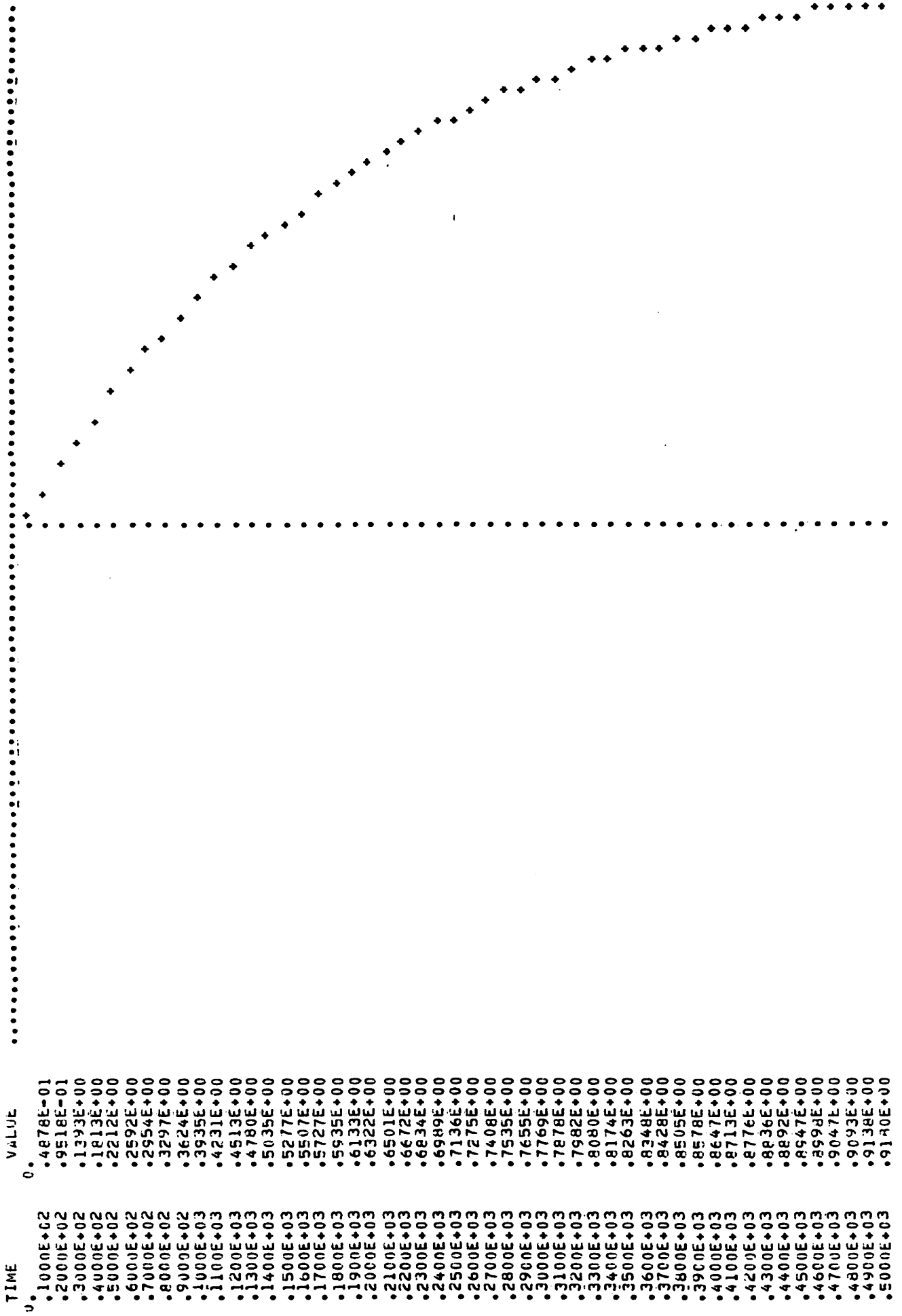
Comments on Sample Problem # 7:

Note that the initial voltage on C_3 has been set to 0.5 volts, which is the steady state value associated with the small time constant (see problem # 6). Failing to do the above would yield incorrect results, since the trapezoidal integration scheme, applied to branch 3, would have a step size to time constant ratio of 10^8 , whereas a ratio of 0.1 is desirable for accurate integration. With the proper initial condition, C_3 becomes, effectively, a voltage source, and the integration problem does not arise.

BRANCH 2 CURRENT



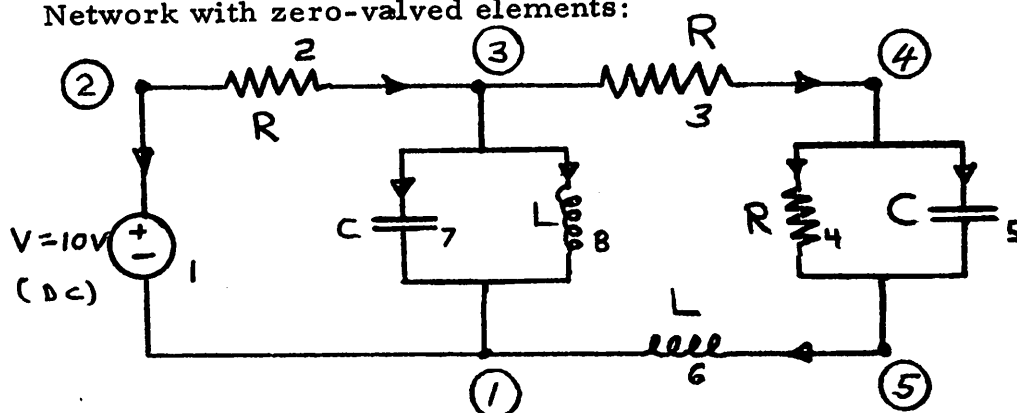
BRANCH 5 VOLTAGE



TIME	VALUE
.100E+02	.4878E+01
.200E+02	.9518E+01
.300E+02	.1393E+00
.400E+02	.1813E+00
.500E+02	.2212E+00
.600E+02	.2592E+00
.700E+02	.2954E+00
.800E+02	.3297E+00
.900E+02	.3624E+00
.100E+03	.3935E+00
.110E+03	.4231E+00
.120E+03	.4513E+00
.130E+03	.4780E+00
.140E+03	.5035E+00
.150E+03	.5277E+00
.160E+03	.5507E+00
.170E+03	.5727E+00
.180E+03	.5935E+00
.190E+03	.6133E+00
.200E+03	.6322E+00
.210E+03	.6501E+00
.220E+03	.6672E+00
.230E+03	.6834E+00
.240E+03	.6989E+00
.250E+03	.7136E+00
.260E+03	.7275E+00
.270E+03	.7408E+00
.280E+03	.7535E+00
.290E+03	.7655E+00
.300E+03	.7769E+00
.310E+03	.7878E+00
.320E+03	.7982E+00
.330E+03	.8080E+00
.340E+03	.8174E+00
.350E+03	.8263E+00
.360E+03	.8348E+00
.370E+03	.8428E+00
.380E+03	.8505E+00
.390E+03	.8578E+00
.400E+03	.8647E+00
.410E+03	.8713E+00
.420E+03	.8776E+00
.430E+03	.8836E+00
.440E+03	.8892E+00
.450E+03	.8947E+00
.460E+03	.8998E+00
.470E+03	.9047E+00
.480E+03	.9093E+00
.490E+03	.9138E+00
.500E+03	.9180E+00

Sample Problem # 8:

Network with zero-valued elements:



$$R_2 = 1 \quad NN = 5$$

$$R_3 = 0 \quad NB = 8$$

$$R_4 = 2$$

$$C_5 = 0$$

$$L_6 = 0$$

$$C_7 = 1$$

$$L_8 = 1$$

Specifications:

- initial time = 0 (TSTART = 0.0)
- final time = 5 sec. (TEND = 5.1)
- time increment = 0.1 sec. (H = 0.1)
- desire tree and F to be outputed (NCONT = 1)
- desire all voltages and currents outputed at every fifteenth time point (NSTEP = 50)
- desire internal, automatic current scaling (NSCALE ≠ 1)

— zero initial conditions

The data cards required for this problem may be seen on the following page.

The central processor time for this problem was 2.49 seconds.

Comments on Sample Problem # 8:

Note that at the initial time point, all capacitances are tree branches and all inductances are links, as desired. For the remaining time points, zero valued R's and L's are tree branches and zero valued C's are links. Such a tree will always exist as long as there are no loops of short circuits (independent voltage sources, zero valued R's and L's), and no cutsets of open circuits (independent current sources and zero valued C's). Should the above conditions not be satisfied, an arithmetic error will result during the execution of the program.

PROBLEM # 8 CONT'D

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
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6 /

7 /

8 /

74

TIME =	0.		
BRANCH	1	VOLTAGE	.10000E+02
BRANCH	2	VOLTAGE	.10000E+02
BRANCH	3	VOLTAGE	0.
BRANCH	4	VOLTAGE	0.
BRANCH	5	VOLTAGE	0.
BRANCH	6	VOLTAGE	0.
BRANCH	7	VOLTAGE	0.
BRANCH	8	VOLTAGE	0.
BRANCH	1	CURRENT	-.10000E+02
BRANCH	2	CURRENT	.10000E+02
BRANCH	3	CURRENT	0.
BRANCH	4	CURRENT	0.
BRANCH	5	CURRENT	0.
BRANCH	6	CURRENT	0.
BRANCH	7	CURRENT	.10000E+02
BRANCH	8	CURRENT	0.

BRANCH	1	VCLTAGE	.10000E+02
BRANCH	2	VCLTAGE	.10060E+02
BRANCH	3	VCLTAGE	0.
BRANCH	4	VCLTAGE	-.59957E-01
BRANCH	5	VCLTAGE	-.59957E-01
BRANCH	6	VCLTAGE	0.
BRANCH	7	VCLTAGE	-.59957E-01
BRANCH	8	VCLTAGE	-.59957E-01
BRANCH	1	CURRENT	-.10060E+02
BRANCH	2	CURRENT	.10060E+02
BRANCH	3	CURRENT	-.29979E-01
BRANCH	4	CURRENT	-.29979E-01
BRANCH	5	CURRENT	0.
BRANCH	6	CURRENT	-.29979E-01
BRANCH	7	CURRENT	-.18740E+00
BRANCH	8	CURRENT	.10277E+02

TIME = .50000E+01

APPENDIX D

CANINE Fortran IV Listing (CDG:64000)

	PROGRAM CANINE(INPUT,OUTPUT)	A	1
	INTEGER CNTSOR	A	2
	INTEGER TEMP	A	3
	INTEGER TYPE	A	4
	INTEGER SORTYPE,CONTYPE	A	5
	INTEGER CONTTEM,SORTEM	A	6
	COMMON /BLOCK1/ NNP(200),NP(200)	A	7
	COMMON /BLOCK2/ IBRAN(200),LEAV(200),LENT(200)	A	8
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	A	9
	COMMON /BLOCK4/ ITBRAN(200),LEAVT(200),LENTT(200)	A	10
	COMMON /BLOCK5/ IOUT(200),NOUT(200),ITEST(200)	A	11
	COMMON /BLOCK6/ TEMP(7),E(200),GRAD(200),CONST(200)	A	12
	COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB	A	13
	COMMON /BLOCK8/ V(200,2),C(200,2)	A	14
	COMMON /BLOCK9/ SORTYPE(200),CONTYPE(200),KONBRAN(200)	A	15
	COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP	A	16
	COMMON /BLOCK11/ SORVAL(5,100),TIMEPT(5,100),SNSOID(5,3),NNI(5)	A	17
	COMMON /BLOCK12/ CONTTEM(200),SORTEM(200),CONDTEM(200),KONTEM(200)	A	18
	COMMON /BK13/ ISTEP,OLDVAL(5),SECVAL(5),OLDTIME(5),SECTIME(5),NNJ(A	19
	15)	A	20
	COMMON /BLOCK14/ KP(5)	A	21
	COMMON /BLOCK15/ NIT,JOUT,NGRAPH,NALLOUT	A	22
	COMMON /BLOCK16/ GRAF(200,5),JGRAPH(5),IGRAPH(5),NPRINT,SCALE,NITT	A	23
	COMMON /BLOCK18/ VAROUT(200)	A	24
	COMMON /BLOCK19/ CNTSOR(200)	A	25
	COMMON /BLOCK20/ NCONT,KLOOP,KPP	A	26
	COMMON /BLOCK21/ NST(5)	A	27
	COMMON /BLOCK22/ CK(200)	A	28
	COMMON /BLOCK24/ SCAL,NSCALE	A	29
	COMMON /BLOCK25/ X(200),Y(200),Z(200,2)	A	30
	DIMENSION HH(20,20)	A	31
	NDATA=0	A	32
	NLNEAR=0	A	33
1	NIT=0	A	34
	NPRINT=0	A	35
	NIC=0	A	36
	IF (NDATA.EQ.0) GO TO 2	A	37
	CALL SECOND (T)	A	38
	TO=T-TU	A	39
	PRINT 13, TO	A	40
2	CALL SECOND (TU)	A	41
	CALL READIN	A	42
	IDEL=NSTEP-1	A	43
	NDATA=NDATA+1	A	44
	CALL KONST	A	45
	CALL INCREM	A	46
	GO TO 9	A	47
3	NIC=NIC+1	A	48
	CALL INCREM	A	49
	IF (NOEL(7).EQ.0) GO TO 5	A	50
	NK=NB-NOEL(7)+1	A	51
	DO 4 I=NK,NB	A	52
	IF (SORTYPE(I).EQ.1HC) GO TO 4	A	53
	C(I,2)=C(I,2)*SCALE	A	54
4	CONTINUE	A	55

5	NIT=0	A	56
	IF (NLNEAR.NE.0) GO TO 6	A	57
	IF (NIC.NE.1) GO TO 11	A	58
6	CALL PT	A	59
	IF (KPP.EQ.0) GO TO 7	A	60
	GO TO 8	A	61
7	SCAL=SCALE	A	62
	GO TO 11	A	63
8	CALL FCSM	A	64
	CALL KONST	A	65
9	IF (NIC.EQ.0) GO TO 11	A	66
	DO 10 I=NN,NB	A	67
	C(I,2)=C(I,2)*SCALE/SCAL	A	68
	C(I,1)=C(I,1)*SCALE/SCAL	A	69
10	CONTINUE	A	70
11	CALL MATSET (HH,NB,NN,NIC)	A	71
	CALL CALCAL	A	72
	NIT=NIT+1	A	73
	IDEL=IDEL+1	A	74
	IF (IDEL.NE.NSTEP) GO TO 12	A	75
	NPRINT=NPRINT+1	A	76
	IF (NGRAPH.GE.1) CALL GRAPH	A	77
	IF (NALLOUT.GE.1) CALL ALLOUT	A	78
	IF (JOUT.GE.1) CALL READOUT	A	79
	IDEL=0	A	80
	IF (NGRAPH.EQ.201) GO TO 1	A	81
12	IF (NIC-NITER) 3,1,1	A	82
C		A	83
13	FORMAT (1H1,20X,*THE CENTRAL PROCESSOR TIME FOR THIS PROBLEM = *,	A	84
	1E15.5,* SECONDS*)	A	85
	END	A	86-

SUBROUTINE READIN

NB IS THE NUMBER OF BRANCHES

NN IS THE NUMBER OF NODES

INTEGER TYPE

INTEGER TEMP

INTEGER SORTYPE,CONTYPE

INTEGER CONTTEM,SORTEM

INTEGER TYTEMP

COMMON /BLOCK1/ NNP(200),NP(200)

COMMON /BLOCK2/ IBRAN(200),LEAV(200),LENT(200)

COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)

COMMON /BLOCK4/ ITBRAN(200),LEAVT(200),LENTT(200)

COMMON /BLOCK5/ IOUT(200),NOUT(200),ITEST(200)

COMMON /BLOCK6/ TEMP(7),ITBB(200),TYTEMP(200),VALTEM(200)

COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB

COMMON /BLOCK9/ SORTYPE(200),CONTYPE(200),KONBRAN(200)

COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP

COMMON /BLOCK11/ SORVAL(5,100),TIMEPT(5,100),SNSOID(5,3),NNI(5)

COMMON /BLOCK12/ CONTTEM(200),SORTEM(200),CONDTEM(200),KONTEM(200)

COMMON /BK13/ ISTEP,OLDVAL(5),SECVAl(5),OLDTIME(5),SECTIME(5),NNJ(15)

COMMON /BLOCK15/ NIT,JOUT,NGRAPH,NALLOUT

COMMON /BLOCK16/ GRAF(200,5),JGRAPH(5),IGRAPH(5),NPRINT,SCALE,NITT

COMMON /BLOCK20/ NCONT,KLOOP

COMMON /BLOCK24/ SCAL,NSCALE

1 ISTEP=0

IJK1=0

IJK2=0

KSOR=0

KCURR=6

READ 19, NN,NB,TSTART,TEND,H,NSTEP,EPS,NCONT

IF (NN.EQ.0) STOP

READ 20, NGRAPH,NALLOUT,JOUT,SCALE,NITT,NSCALE

PRINT 21, TSTART,TEND,H

PRINT 22, NN,NB,SCALE,NSCALE

PRINT 23, NSTEP

IF (H.EQ.0.0) GO TO 2

NITER=(TEND-TSTART)/H

GO TO 3

2 NITER=0

3 DO 9 I=1,NB

READ 24, TYPE(I),IBRAN(I),SORTYPE(I),CONTYPE(I),KONBRAN(I),LEAV(I)

1,LENT(I),NCARDS,VALUE(I),COND(I)

IF (NCARDS.EQ.0) GO TO 9

IF (TYPE(I).EQ.1HJ) GO TO 4

IF (SORTYPE(I).EQ.1HS.OR.SORTYPE(I).EQ.1HE) GO TO 5

IF (SORTYPE(I).EQ.1HP.OR.SORTYPE(I).EQ.1HT) GO TO 6

4 ISTEP=ISTEP+1

IF (SORTYPE(I).EQ.1HP.OR.SORTYPE(I).EQ.1HT) GO TO 8

IF (SORTYPE(I).EQ.1HS.OR.SORTYPE(I).EQ.1HE) GO TO 7

GO TO 9

5 KSOR=KSOR+1

NNJ(KSOR)=0

READ 25, (SNSOID(KSOR,J),J=1,3)

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B	55

	GO TO 9	B	56
6	KSOR=KSOR+1	B	57
	NNJ(KSOR)=0	B	58
	READ 26, NNI(KSOR)	B	59
	NNN=NNI(KSOR)	B	60
	READ 27, (SORVAL(KSOR,J),J=1,NNN)	B	61
	READ 27, (TIMEPT(KSOR,J),J=1,NNN)	B	62
	GO TO 9	B	63
7	KCURR=KCURR-1	B	64
	NNJ(KCURR)=0	B	65
	READ 25, (SNSOID(KCURR,J),J=1,3)	B	66
	GO TO 9	B	67
8	KCURR=KCURR-1	B	68
	NNJ(KCURR)=0	B	69
	READ 26, NNI(KCURR)	B	70
	NNN=NNI(KCURR)	B	71
	READ 27, (SORVAL(KCURR,J),J=1,NNN)	B	72
	READ 27, (TIMEPT(KCURR,J),J=1,NNN)	B	73
9	CONTINUE	B	74
	IF (NGRAPH.EQ.0) GO TO 10	B	75
	READ 28, ((IGRAPH(I),JGRAPH(I)),I=1,NGRAPH)	B	76
10	IF (NALLOUT.GE.1.OR.NGRAPH.GE.1) GO TO 11	B	77
	READ 28, ((IOUT(I),ITEST(I)),I=1,JOUT)	B	78
11	PRINT 18	B	79
	PRINT 29	B	80
	DO 12 I=1,NB	B	81
	PRINT 30, IBRAN(I),TYPE(I),VALUE(I),LEAV(I),LENT(I),COND(I)	B	82
12	CONTINUE	B	83
	DO 14 I=1,NB	B	84
	IF (SORTYPE(I).NE.1H) GO TO 13	B	85
	GO TO 14	B	86
13	IF (IJK1.EQ.0) PRINT 31	B	87
	IJK1=1	B	88
	A=7HVOLTAGE	B	89
	IF (TYPE(I).EQ.1HJ) A=7HCURRENT	B	90
	PRINT 32, A,IBRAN(I),SORTYPE(I)	B	91
14	CONTINUE	B	92
	DO 17 I=1,NB	B	93
	IF (CONTYPE(I).NE.1H) GO TO 15	B	94
	GO TO 17	B	95
15	IF (IJK2.EQ.0) PRINT 33	B	96
	IJK2=1	B	97
	IF (TYPE(I).EQ.1HI) GO TO 16	B	98
	A=7HCURRENT	B	99
	IF (CONTYPE(I).EQ.1HV) A=7HVOLTAGE	B	100
	PRINT 34, A,IBRAN(I),KONBRAN(I)	B	101
	GO TO 17	B	102
16	A=7HCURRENT	B	103
	IF (CONTYPE(I).EQ.1HV) A=7HVOLTAGE	B	104
	PRINT 35, A,IBRAN(I),KONBRAN(I)	B	105
17	CONTINUE	B	106
	IDIMEN=NB-NN+1	B	107
	KLOOP=0	B	108
	CALL PT	B	109
	IF (KLOOP.EQ.1) GO TO 1	B	110

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CALL FCSM
RETURN
C
18  FORMAT (1H1,55X,*THIS IS THE GIVEN NETWORK *)
19  FORMAT (I5,I5,E15.3,E15.3,E15.3,I5,E15.3,I5)
20  FORMAT (3I5,E15.5,I5,I5)
21  FORMAT (1H1,//////,40X,* STARTI
    1NG TIME = *,E15.5,*   END TIME = *,E15.5,///,40X,*STEP SIZE = *,
    2 E15.5)
22  FORMAT (1H0,///,30X,*NUMBER OF NODES = *,I5,*   NUMBER OF BRANCHE
    1S = *,I5,///,30X,*SCALE FACTOR = *,E15.5,///,30X,
    2 *NSCALE = *,I5)
23  FORMAT (1H0,///,30X,* NUMBER OF TIME ITERATIONS PER OUTPUT = *,I5)
24  FORMAT (A1,I3,A1,A1,I3,1X,I2,1X,I2,1X,I2,2X,E15.4,E15.4)
25  FORMAT ( 3E10.3)
26  FORMAT ( I5 )
27  FORMAT ( 8E10.3 )
28  FORMAT (2I5)
29  FORMAT (1H0,///,55X,*UNITS ARE OHMS, FARADS AND HENRYS *)
30  FORMAT (1H0, 3X,*BRANCH NUMBER *,2X,I3,4X,* IS A      *,A1,*   OF
    1 VALUE *,E12.5,* LEAVING NODE  *,I3,* AND ENTERING NODE  *,I3,
    22X,* COND = *,E10.3)
31  FORMAT (1H1,//////,30X,*INDEPENDENT SOURCES*,///)
32  FORMAT (1H0,10X,A7, * SOURCE BRANCH *,I3,* IS OF TYPE  *,A1)
33  FORMAT (1H-,///,30X,*CONTROLLED SOURCES *,///)
34  FORMAT (1H0,10X,A7,* CONTROLLED VOLTAGE SOURCE*,I3,* IS CONTROLLED
    1 BY BRANCH*,I5)
35  FORMAT (1H0,10X,A7,* CONTROLLED CURRENT SOURCE*,I3,* IS CONTROLLED
    1 BY BRANCH*,I5)
    END

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SUBROUTINE PT
INTEGER TEMP01,TEMP02,TEMP03,TEMP04,TEMP06,TEMP07,TEMP09
INTEGER TYTEMP
INTEGER TYPE
INTEGER TEMP
INTEGER CONTYPE,SORTYPE
INTEGER SORTEM,CONTEM
INTEGER CNTSOR
COMMON /BLOCK1/ NNP(200),NP(200)
COMMON /BLOCK2/ IRAN(200),LEAV(200),LENT(200)
COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)
COMMON /BLOCK4/ ITRAN(200),LEAVT(200),LENTT(200)
COMMON /BLOCK5/ IOUT(200),NOUT(200),ITEST(200)
COMMON /BLOCK6/ TEMP(7),ITRB(200),TYTEMP(200),VALTEMP(200)
COMMON /BLOCK7/ DIMEN,ALPHA,FUNCT,NIC,NITER,H,FPS,NN,NB
COMMON /BLOCK8/ V(200,2),C(200,2)
COMMON /BLOCK9/ SORTYPE(200),CONTYPE(200),KONBRAN(200)
COMMON /BLOCK10/ COND(200),IDEL,ISTART,TEMD,NSTEP
COMMON /BLOCK12/ CONTEM(200),SORTEM(200),CONDEM(200),KONTEM(200)
COMMON /BLOCK15/ NIT,JOUT,MGRAPH,NALLOUT
COMMON /BLOCK16/ GRAF(200,5),JGRAPH(5),IGRAPH(5),NPRINT,SCALE,NIT
COMMON /BLOCK18/ CONST(200)
COMMON /BLOCK19/ CNTSOR(200)
COMMON /BLOCK20/ MCONT,KLOOP,KPP
COMMON /BLOCK21/ NST(5)
KK=NN-1
KM=0
KKT=0
IF (NIC.NF.0) GO TO 5
TEMP(1)=1HE
TEMP(2)=1HV
TEMP(3)=1HC
TEMP(4)=1HR
TEMP(5)=1HL
TEMP(6)=1HI
TEMP(7)=1HU
DO 3 K=1,7
KT=0
DO 2 I=1,NB
IF (TYPE(I).EQ.TEMP(K)) GO TO 1
GO TO 2
KM=KM+1
ITBRAN(KM)=I
TYTEMP(KM)=TEMP(K)
VALTEMP(KM)=VALUF(I)
KT=KT+1
CONTEM(KM)=CONTYPE(I)
SORTEM(KM)=SORTYPE(I)
CONDEM(KM)=COND(I)
KONTEM(KM)=KONBRAN(I)
CONTINUE
NOEL(K)=KT
CONTINUE
DO 4 I=1,NB
K=ITBRAN(I)

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56 C LEAVT(I)=LEAV(K)
57 C LENT(I)=LENT(K)
58 C TYPE(I)=TYTEMP(I)
59 C VALUE(I)=VALTEMP(I)
60 C CONTYPE(I)=CONTTEMP(I)
61 C SORTYPE(I)=SORTTEMP(I)
62 C COND(I)=CONDTEMP(I)
63 C KONBRAN(I)=KONTEMP(I)
64 C CONTINUE
65 C IF (NOEL(4)*EQ.0) GO TO 15
66 C N=NOEL(1)+NOEL(2)+NOEL(3)+1
67 C MM=N+NOEL(4)-1
68 C GO TO 6
69 C CONTINUE
70 C MM=NR-NOEL(7)
71 C N=NOEL(1)+1
72 C M=MM-1
73 C DO 7 I=N,MM
74 C IF (TYPE(I).EQ.1HV) CONST(I)=1.0F-50
75 C IF (TYPE(I).EQ.1HC) GO TO 8
76 C IF (TYPE(I).EQ.1HR) CONST(I)=VALUE(I)
77 C IF (TYPE(I).EQ.1HL) CONST(I)=2.0*VALUE(I)/H
78 C IF (TYPE(I).EQ.1HI) CONST(I)=1.0F+50
79 C CONTINUE
80 C GO TO 9
81 C IF (VALUE(I).EQ.0.0) CONST(I)=1.0F+51
82 C IF (VALUE(I).NE.0.0) CONST(I)=H/(2.0*VALUE(I))
83 C GO TO 7
84 C KPP=0
84A C IF (N.GT.M) GO TO 15
85 C DO 14 I=N,M
86 C KP=0
87 C AMIN=CONST(I)
88 C K=I+1
89 C DO 11 J=K,MM
90 C IF (CONST(J).LT.AMIN) GO TO 10
91 C GO TO 11
92 C AMIN=CONST(J)
93 C NP(I)=J
94 C KP=1
95 C KPP=1
96 C CONTINUE
97 C IF (KP.EQ.0) GO TO 14
98 C J=NP(I)
99 C TRAMP1=TRAN(I)
100 C TRAMP2=LEAVT(I)
101 C TRAMP3=LENT(I)
102 C TRAMP4=TYPE(I)
103 C TRAMP5=VALUE(I)
104 C TRAMP6=CONTYPE(I)
105 C TRAMP7=SORTYPE(I)
106 C TRAMP8=COND(I)
107 C TRAMP9=KONBRAN(I)
108 C TRAMP10=CONST(I)
109 C IF (NIC.EQ.0) GO TO 12

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	TFMP11=V(I,2)	C 110
	TFMP12=C(I,2)	C 111
	TFMP13=V(I,1)	C 112
	TEMP14=C(I,1)	C 113
12	ITBRAN(I)=ITBRAN(J)	C 114
	LFAVT(I)=LEAVT(J)	C 115
	LFNTT(I)=LFNTT(J)	C 116
	TYPE(I)=TYPE(J)	C 117
	VALUF(I)=VALUJE(J)	C 118
	CONTYPE(I)=CONTYPE(J)	C 119
	SORTYPE(I)=SORTYPE(J)	C 120
	COND(I)=COND(J)	C 121
	KONBRAN(I)=KONBRAN(J)	C 122
	CONST(I)=CONST(J)	C 123
	IF (NIC.EQ.0) GO TO 13	C 124
	V(I,2)=V(J,2)	C 125
	C(I,2)=C(J,2)	C 126
	V(I,1)=V(J,1)	C 127
	C(I,1)=C(J,1)	C 128
13	ITBRAN(J)=TFMP01	C 129
	LEAVT(J)=TFMP02	C 130
	LFNTT(J)=TFMP03	C 131
	TYPE(J)=TFMP04	C 132
	VALUF(J)=TFMP05	C 133
	CONTYPE(J)=TFMP06	C 134
	SORTYPE(J)=TFMP07	C 135
	COND(J)=TFMP08	C 136
	KONBRAN(J)=TFMP09	C 137
	CONST(J)=TFMP10	C 138
	IF (NIC.EQ.0) GO TO 14	C 139
	V(J,2)=TFMP11	C 140
	C(J,2)=TFMP12	C 141
	V(J,1)=TFMP13	C 142
	C(J,1)=TFMP14	C 143
14	CONTINUE	C 144
15	IF (2.GT.KK) GO TO 32	C 144A
	DO 25 I=2, KK	C 145
16	NF=LFNTT(I)	C 146
	NI=LEAVT(I)	C 147
	NP(1)=I	C 148
	NMP(1)=1	C 149
	M=I-1	C 150
	MT=0	C 151
	KT=1	C 152
17	DO 19 JJJ=1, M	C 153
	J=M+1-JJJ	C 154
	IF (MT.EQ.J) GO TO 18	C 155
	IF (LEAVT(J).EQ.NF) GO TO 23	C 156
	IF (LFNTT(J).EQ.NF) GO TO 24	C 157
18	CONTINUE	C 158
19	CONTINUE	C 159
20	IF (KT.EQ.1) GO TO 25	C 160
	KA=NMP(KT)	C 161
	KB=NP(KT)	C 162
	M=KB-1	C 163

	IF (M.EQ.0) GO TO 21	C 164
	MT=NP(KT-1)	C 165
	KT=KT-1	C 166
	IF (KA.EQ.-1) GO TO 22	C 167
	NF=LFAVT(KB)	C 168
	GO TO 17	C 169
21	KT=KT-1	C 170
	GO TO 20	C 171
22	NF=LFNTT(KB)	C 172
	GO TO 17	C 173
23	IF (LFNTT(J).EQ.NI) GO TO 26	C 174
	NF=LFNTT(J)	C 175
	KT=KT+1	C 176
	NP(KT)=J	C 177
	NMP(KT)=1	C 178
	MT=J	C 179
	M=I-1	C 180
	GO TO 17	C 181
24	IF (LFAVT(J).EQ.NL) GO TO 26	C 182
	NF=LFAVT(J)	C 183
	KT=KT+1	C 184
	NP(KT)=J	C 185
	NMP(KT)=-1	C 186
	MT=J	C 187
	M=I-1	C 188
	GO TO 17	C 189
25	CONTINUE	C 190
	GO TO 32	C 191
26	LAF=NOEL(1)	C 192
	IF (I.LF.LAF) GO TO 52	C 193
27	TEMPO1=ITBRAN(I)	C 194
	TEMPO2=LFAVT(I)	C 195
	TEMPO3=LFNTT(I)	C 196
	TEMPO4=TYPE(I)	C 197
	TEMPO5=VALUE(I)	C 198
	TEMPO6=CONTYPE(I)	C 199
	TEMPO7=SORTYPE(I)	C 200
	TEMPO8=COND(I)	C 201
	TEMPO9=KOMBRAN(I)	C 202
	IF (NIC.EQ.0) GO TO 28	C 203
	TEMP11=V(I,2)	C 204
	TEMP12=C(I,2)	C 205
	TEMP13=V(I,1)	C 206
	TEMP14=C(I,1)	C 207
28	CONTINUE	C 208
	NIB=NR-1	C 209
	IF (NIC.NE.0) NIB=NR-NOEL(7)-1	C 210
	DO 30 JN=I,NIB	C 211
	JF=JN+1	C 212
	ITBRAN(JN)=ITBRAN(JF)	C 213
	LFAVT(JN)=LFAVT(JF)	C 214
	LFNTT(JN)=LFNTT(JF)	C 215
	TYPE(JN)=TYPE(JF)	C 216
	VALUE(JN)=VALUE(JF)	C 217
	CONTYPE(JN)=CONTYPE(JF)	C 218

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C 219 SORTYPE(JN)=SORTYPE(JF)
C 220 COND(JN)=COND(JF)
C 221 KONBRAN(JN)=KONBRAN(JF)
C 222 IF (NIC.FO.O) GO TO 29
C 223 V(JN,2)=V(JF,2)
C 224 C(JN,2)=C(JF,2)
C 225 V(JN,1)=V(JF,1)
C 226 C(JN,1)=C(JF,1)
C 227 CONTINUE
C 228 CONTINUE
C 229 MZ=NR
C 230 IF (NIC.NF.O) MZ=NR-NFEL(7)
C 231 ITRAN(MZ)=TEMP01
C 232 LEAVT(MZ)=TEMP02
C 233 LENT(MZ)=TEMP03
C 234 TYP(MZ)=TEMP04
C 235 VALIF(MZ)=TEMP05
C 236 CONTYPE(MZ)=TEMP06
C 237 SORTYPE(MZ)=TEMP07
C 238 COND(MZ)=TEMP08
C 239 KONBRAN(MZ)=TEMP09
C 240 IF (NIC.FO.O) GO TO 31
C 241 V(MZ,2)=TEMP11
C 242 C(MZ,2)=TEMP12
C 243 V(MZ,1)=TEMP13
C 244 C(MZ,1)=TEMP14
C 245 CONTINUE
C 246 IF (KKT1.FO.1) GO TO 35
C 247 GO TO 16
C 248 CONTINUE
C 249 DO 33 I=1,KK
C 250 IF (TYPE(L).FO.TEMP(7)) GO TO 32
C 251 CONTINUE
C 252 IF (NIC.NF.O) GO TO 36
C 253 DO 35 I=MN,NR
C 254 IF (TYPE(I).FO.TEMP(7)) GO TO 34
C 255 GO TO 35
C 256 KKT1=1
C 257 GO TO 27
C 258 CONTINUE
C 259 DO 37 I=1,NR
C 260 K=ITRAN(I)
C 261 MP(I)=IRBAN(K)
C 262 CONTINUE
C 263 DO 38 I=1,NR
C 264 CONTOR(I)=0
C 265 CONTINUE
C 266 IF (JOUT.FO.O) GO TO 41
C 267 DO 40 I=1,JOUT
C 268 K=0
C 269 K=K+1
C 270 IF (IOUT(I).NF.MP(K)) GO TO 39
C 271 NOUT(I)=K
C 272 CONTINUE
C 273 IF (NGRAPH.FO.O) GO TO 44

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C 274 DO 42 I=1,NGRAPH
C 275 K=K+1
C 276 IF ((GRAPH(I)*NF*NP(K)) GO TO 42
C 277 NST(I)=K
C 278 CONTINUE
C 279 N=NOEL(1)+1
C 280 M=NR-NOEL(7)
C 281 DO 50 I=N,M
C 282 IF (TYPE(1)*EO.1H1) GO TO 45
C 283 IF (TYPE(1)*EO.1HV) GO TO 45
C 284 GO TO 50
C 285 K=KONBRAN(I)
C 286 L=0
C 287 L=L+1
C 288 IF (L*GT*NOEL(1)) GO TO 47
C 289 IF (NP(L)*NF*K) GO TO 46
C 290 GO TO 49
C 291 L=NR-NOEL(7)
C 292 L=L+1
C 293 IF (NP(L)*NF*K) GO TO 48
C 294 CNTSOR(1)=L
C 295 CNTSOR(I)=I
C 296 CONTINUE
C 297 IF (NGMT*EO.0) GO TO 54
C 298 PRINT 55
C 299 PRINT 56, ((,NP(I)),1=1,KK)
C 300 PRINT 57, ((,NP(I)),1=NN,NR)
C 301 PRINT 58
C 302 PRINT 58
C 303 DO 51 I=1,NR
C 304 PRINT 59, NP(I),TYPE(I),VALUE(I),LEAVT(I),LENTT(I),COND(I)
C 305 CONTINUE
C 306 RETURN
C 307 PRINT 60
C 308 KLOOP=1
C 309 RETURN
C 310 PRINT 61
C 311 KLOOP=1
C 312 RETURN
C 313
C 314 FORMAT (1H1,20X,*CORRESPONDENCE BETWEEN ORIGINAL TOPOLOGY AND NEW
C 315 TOPOLOGY*,///)
C 316 FORMAT (1H0,30X,*TREE BRANCH*,14,5X,*CORRESPONDS TO BRANCH *,14)
C 317 FORMAT (1H0,33X,* LINK *,2X,14,5X,*CORRESPONDS TO BRANCH *,14)
C 318 FORMAT (1H1)
C 319 FORMAT (1H0, 3X,*BRANCH NUMBER *,2X,13,4X,* IS A
C 320 *A1,* OF
C 321 VALUE *.F12.5,* LEAVING NODE *,13,* AND ENTERING NODE *,13,
C 322 22X,* COND = *,E10.3)
C 323 FORMAT (1H0,30X,*THERE IS A VOLTAGE LOOP IN NETWORK*)
C 324- END
FORMAT (1H0,30X,*THERE IS A CURRENT SOURCE CUTSET IN NETWORK*)

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	SUBROUTINE FCSM	D	1
	INTEGER TEMP	D	2
	INTEGER TYPE	D	3
	INTEGER TYTEMP	D	4
	COMMON /BLOCK1/ NNP(200),NP(200)	D	5
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	D	6
	COMMON /BLOCK4/ ITBRAN(200),LEAVT(200),LENTT(200)	D	7
	COMMON /BLOCK5/ IOUT(10),ITEST(10),NOUT(10)	D	8
	COMMON /BLOCK6/ TEMP(7),ITBB(200),TYTEMP(200),VALTEM(200)	D	9
	COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB	D	10
	COMMON /BLOCK20/ NCONT,KLOOP	D	11
C	SET MATRIX TO ZERO	D	12
	KK=NN-1	D	13
	NLB=NB-NN+1	D	14
	DO 1 I=1,NLB	D	15
	DO 1 J=1,KK	D	16
	F(J,I)=0.0	D	17
1	CONTINUE	D	18
	DO 8 I=NN,NB	D	19
	NE=LENTT(I)	D	20
	NL=LEAVT(I)	D	21
	IO=I-NN+1	D	22
C	NP STORES THE PREVIOUS TREE BRANCH	D	23
C	NNP STORES ITS DIRECTION	D	24
	NP(1)=I	D	25
	NNP(1)=1	D	26
	M=1	D	27
	KT=1	D	28
2	DO 3 J=M,KK	D	29
	IF (J.EQ.NP(KT)) GO TO 3	D	30
	IF (LEAVT(J).EQ.NE) GO TO 6	D	31
	IF (LENTT(J).EQ.NE) GO TO 7	D	32
3	CONTINUE	D	33
4	M=NP(KT)+1	D	34
	KA=NNP(KT)	D	35
	KB=NP(KT)	D	36
	F(KB,IO)=0.0	D	37
	KT=KT-1	D	38
	IF (M.GE.NN) GO TO 4	D	39
	IF (KA.EQ.1) GO TO 5	D	40
	NE=LENTT(KB)	D	41
	GO TO 2	D	42
5	NE=LEAVT(KB)	D	43
	GO TO 2	D	44
6	F(J,IO)=-1.0	D	45
	KT=KT+1	D	46
	IF (LENTT(J).EQ.NL) GO TO 8	D	47
	NE=LENTT(J)	D	48
	NP(KT)=J	D	49
	NNP(KT)=1	D	50
	M=1	D	51
	GO TO 2	D	52
7	F(J,IO)=1.0	D	53
	KT=KT+1	D	54
	IF (LEAVT(J).EQ.NL) GO TO 8	D	55

	NE=LEAVT(J)	D	56
	NP(KT)=J	D	57
	NNP(KT)=-1	D	58
	M=1	D	59
	GO TO 2	D	60
8	CONTINUE	D	61
	IF (NCONT.EQ.0) GO TO 16	D	62
	NLB=NB-NN+1	D	63
	KK=NN-1	D	64
	NCOUNT=-1	D	65
	NT=NLB	D	66
	NPAGE=1	D	67
	PRINT 17, NPAGE	D	68
	PRINT 18	D	69
	PRINT 19, (J,J=1,NLB)	D	70
9	NT=NT-25	D	71
	NCOUNT=NCOUNT+1	D	72
	NS1=1+25*NCOUNT	D	73
	NS2=25+25*NCOUNT	D	74
	IF (NT.LE.0) GO TO 11	D	75
	DO 10 I=1,KK	D	76
	PRINT 20, I,(F(I,J),J=NS1,NS2)	D	77
10	CONTINUE	D	78
	NPAGE=NPAGE+1	D	79
	GO TO 9	D	80
11	IF (NT.EQ.0) GO TO 12	D	81
	GO TO 13	D	82
12	NS3=1	D	83
	NS4=25	D	84
	GO TO 14	D	85
13	NT=NT+25	D	86
	NS3=NS1	D	87
	NS4=NS1+NT-1	D	88
14	CONTINUE	D	89
	DO 15 I=1,KK	D	90
	PRINT 20, I,(F(I,J),J=NS3,NS4)	D	91
15	CONTINUE	D	92
16	RETURN	D	93
C		D	94
17	FORMAT (1H1,40X,*FUNDAMENTAL CUT SET MATRIX *,5X,*PAGE *,I3)	D	95
18	FORMAT (///)	D	96
19	FORMAT (1H0,7X,25(2X,I2,1X))	D	97
20	FORMAT (1H0,I3,3X,25(2X,F3.0))	D	98
	END	D	99-

	SUBROUTINE KONST	E	1
C	CALCULATION OF CONSTANTS RELATED TO ELEMENT VALUES FOR USE IN BRAN	E	2
C	RELATIONS AND GRADIENT	E	3
	INTEGER TEMP	E	4
	INTEGER TYPE	E	5
	INTEGER SORTYPE,CONTYPE	E	6
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOFL(7)	E	7
	COMMON /BLOCK6/ TEMP(7),F(200),GRAD(200),CONST(200)	E	8
	COMMON /BLOCK7/ IDIRFN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NS	E	9
	COMMON /BLOCK8/ V(200,2),C(200,2)	E	10
	COMMON /BLOCK9/ SORTYPE(200),CONTYPE(200),KONBRAN(200)	E	11
	COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP	E	12
	COMMON /BLOCK11/ SORVAL(5,100),TIMEPT(5,100),CONFOID(5,3),NNI(5)	F	13
	COMMON /BK13/ ISTEP,OLDVAL(5),SECVAL(5),OLDTIME(5),SECTIME(5),NNJ(E	14
	15)	E	15
	COMMON /BLOCK14/ NP(5)	E	16
	COMMON /BLOCK16/ GRAF(200,5),JGRAPH(5),IGRAPH(5),NPRINT,SCALE,NITT	E	17
	COMMON /BLOCK24/ SCAL,NSCALE	E	18
	IF (NIC.NE.0) GO TO 2	E	19
	DO 1 I=1,5	E	20
	SECTIME(I)=TIMEPT(I,2)	E	21
	OLDTIME(I)=TIMEPT(I,1)	E	22
	SECVAL(I)=SORVAL(I,2)	E	23
	OLDVAL(I)=SORVAL(I,1)	E	24
	NP(I)=2	E	25
1	CONTINUE	E	26
2	SCAL=SCALE	E	27
	IF (NSCALE.EQ.1) GO TO 5	E	28
	KW=0	E	29
	DO 4 I=NN,NS	E	30
	IF (TYPE(I).EQ.1HR) GO TO 3	E	31
	GO TO 4	E	32
3	IF (KW.EQ.0) SCALE=VALUE(I)	E	33
	KW=1	E	34
	IF (VALUE(I).LT.SCAL) SCALE=VALUE(I)	E	35
4	CONTINUE	E	36
	IF (KW.EQ.1) GO TO 5	ADD	1
	DO 135 I=1,NN	ADD	2
	IF (TYPE(I).EQ.1HR) GO TO 136	ADD	3
	GO TO 135	ADD	4
136	IF (KW.EQ.0) SCALE=VALUE(I)	ADD	5
	KW=1	ADD	6
	IF (VALUE(I).GT.SCAL) SCALE=VALUE(I)	ADD	7
135	CONTINUE	ADD	8
	IF (KW.EQ.0) SCALE=1.0	ADD	9
	IF (SCALE.EQ.0.0) SCALE=1.0	ADD	10
5	N=NN-1	E	38
	DO 12 I=1,N	E	39
	IF (TYPE(I).EQ.1HF) GO TO 6	E	40
	IF (TYPE(I).EQ.1HV) GO TO 7	E	41
	IF (TYPE(I).EQ.1HC) GO TO 8	F	42
	IF (TYPE(I).EQ.1HR) GO TO 9	E	43
	IF (TYPE(I).EQ.1HL) GO TO 10	F	44
	IF (TYPE(I).EQ.1HI) GO TO 11	E	45
	GO TO 12	E	46

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6  IF (NIC.NE.0) GO TO 12
    V(I,2)=COND(I)
    CONST(I)=0.0
    GO TO 12
7  CONST(I)=VALUE(I)
    IF (CONTYPE(I).EQ.1HI) CONST(I)=CONST(I)/SCALE
    IF (NIC.NE.0) GO TO 12
    V(I,2)=COND(I)
    GO TO 12
8  CONST(I)=h/(2.0*VALUE(I)*SCALE)
    IF (NIC.NE.0) GO TO 12
    V(I,2)=COND(I)
    GO TO 12
9  CONST(I)=VALUE(I)/SCALE
    IF (NIC.NE.0) GO TO 12
    V(I,2)=COND(I)
    GO TO 12
10 CONST(I)=2.0*VALUE(I)/(H*SCALE)
    IF (NIC.NE.0) GO TO 12
    V(I,2)=0.0
    GO TO 12
11 CONST(I)=VALUE(I)
    IF (CONTYPE(I).EQ.1HV) CONST(I)=CONST(I)*SCALE
    IF (NIC.NE.0) GO TO 12
    V(I,2)=0.
12 CONTINUE
    DO 19 I=NN,NR
    IF (TYPE(I).EQ.1HJ) GO TO 13
    IF (TYPE(I).EQ.1HV) GO TO 14
    IF (TYPE(I).EQ.1HC) GO TO 15
    IF (TYPE(I).EQ.1HR) GO TO 16
    IF (TYPE(I).EQ.1HL) GO TO 17
    IF (TYPE(I).EQ.1HI) GO TO 18
    GO TO 19
13 IF (NIC.NE.0) GO TO 19
    C(I,2)=COND(I)*SCALE
    CONST(I)=0.0
    GO TO 19
14 CONST(I)=VALUE(I)
    IF (CONTYPE(I).EQ.1HI) CONST(I)=CONST(I)/SCALE
    IF (NIC.NE.0) GO TO 19
    C(I,2)=0.0
    GO TO 19
15 CONST(I)=2.0*VALUE(I)*SCALE/H
    IF (NIC.NE.0) GO TO 19
    C(I,2)=0.0
    GO TO 19
16 CONST(I)=1.0/VALUE(I)*SCALE
    IF (NIC.NE.0) GO TO 19
    C(I,2)=COND(I)*SCALE
    GO TO 19
17 CONST(I)=H*SCALE/(2.0*VALUE(I))
    IF (NIC.NE.0) GO TO 19
    C(I,2)=COND(I)*SCALE
    GO TO 19

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18  CONST(I)=VALUE(I)
    IF (CONTPF(I).EQ.14V) CONST(I)=CONST(I)*SCALE
    IF (NIC.NE.0) GO TO 19
    C(I,2)=COND(I)*SCALE
19  CONTINUE
    RETURN
    END
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F 102
E 103
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E 106
F 107
E 108-
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	SUBROUTINE CALCAL	F	1
	INTEGER CNTSOR	F	2
	INTEGER TYPE	F	3
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	F	4
	COMMON /BLOCK8/ V(200,2),C(200,2)	F	5
	COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB	F	6
	COMMON /BLOCK19/ CNTSOR(200)	F	7
	N=NN-1	F	8
	DO 1 I=1,N	F	9
	C(I,2)=0.0	F	10
	DO 1 J=NN,NB	F	11
	C(I,2)=C(I,2)-F(I,J-N)*C(J,2)	F	12
1	CONTINUE	F	13
	DO 2 I=NN,NB	F	14
	V(I,2)=0.0	F	15
	DO 2 J=1,N	F	16
	V(I,2)=V(I,2)+F(J,I-N)*V(J,2)	F	17
2	CONTINUE	F	18
	RETURN	F	19
	END	F	20-

	SUBROUTINE INCREM	G	1
	INTEGER TEMP	G	2
	INTEGER TYPE	G	3
	INTEGER SORTYPE,CONTYPE	G	4
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	G	5
	COMMON /BLOCK6/ TEMP(7),F(200),GRAD(200),CONST(200)	G	6
	COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB	G	7
	COMMON /BLOCK8/ V(200,2),C(200,2)	G	8
	COMMON /BLOCK9/ SORTYPE(200),CONTYPE(200),KONBRAN(200)	G	9
	COMMON /BLOCK10/ COND(200),IDFL,TSTART,TEND,NSTEP	G	10
	COMMON /BLOCK11/ SORVAL(5,100),TIMEPT(5,100),SNSOID(5,3),NNI(5)	G	11
	COMMON /BK13/ ISTEP,OLDVAL(5),SECVAL(5),OLDTIME(5),SECTIME(5),NNJ(G	12
	15)	G	13
	COMMON /BLOCK14/ NP(5)	G	14
	LOGICAL BOOL	G	15
	IF (NIC.EQ.0) GO TO 3	G	16
	BOOL=.TRUE.	G	17
	DO 1 I=1,NB	G	18
	V(I,1)=V(I,2)	G	19
1	CONTINUE	G	20
	DO 2 I=1,NB	G	21
	C(I,1)=C(I,2)	G	22
2	CONTINUE	G	23
3	TIME=TSTART+NIC*H	G	24
	M=NOEL(1)+NOEL(7)	G	25
	K=0	G	26
	DO 15 I=1,M	G	27
	J=I	G	28
	IF (I.GE.NOEL(1)+1) J=NB-I+NOEL(1)+1	G	29
	IF (J.GT.I.AND.BOOL) GO TO 4	G	30
	GO TO 5	G	31
4	BOOL=.FALSE.	G	32
	K=5-ISTEP	G	33
5	IF (SORTYPE(J).EQ.1HC) GO TO 15	G	34
	K=K+1	G	35
	IF (SORTYPE(J).EQ.1HF.OR.SORTYPE(J).EQ.1HS) GO TO 8	G	36
	IF (SORTYPE(J).EQ.1HP) GO TO 12	G	37
	IF (TIME.LE.SECTIME(K)) GO TO 6	G	38
	IF (NNI(K).LE.NP(K)) GO TO 13	G	39
	NP(K)=NP(K)+1	G	40
	NPR=NP(K)	G	41
	OLDTIME(K)=SECTIME(K)	G	42
	SECTIME(K)=TIMEPT(K,NPR)	G	43
	OLDVAL(K)=SECVAL(K)	G	44
	SECVAL(K)=SORVAL(K,NPR)	G	45
6	IF (I.GE.NOEL(1)+1) GO TO 7	G	46
	V(J,2)=OLDVAL(K)+(SECVAL(K)-OLDVAL(K))*(TIME-OLDTIME(K))/(SECTIME(G	47
	1K)-OLDTIME(K))	G	48
	GO TO 15	G	49
7	C(J,2)=OLDVAL(K)+(SECVAL(K)-OLDVAL(K))*(TIME-OLDTIME(K))/(SECTIME(G	50
	1K)-OLDTIME(K))	G	51
	GO TO 15	G	52
8	W=SNSOID(K,2)	G	53
	T=SNSOID(K,3)	G	54
	IF (SORTYPE(J).EQ.1HS) GO TO 10	G	55

	IF (J.GT.1) GO TO 9	G	56
	V(J,2)=SNSOID(K,1)*EXP(W*TIME-T)	G	57
	GO TO 15	G	58
9	C(J,2)=SNSOID(K,1)*EXP(W*TIME-T)	G	59
	GO TO 15	G	60
10	IF (J.GT.1) GO TO 11	G	61
	V(J,2)=SNSOID(K,1)*SIN(W*TIME-T)	G	62
	GO TO 15	G	63
11	C(J,2)=SNSOID(K,1)*SIN(W*TIME-T)	G	64
	GO TO 15	G	65
12	CALL PERIOD (K,J)	G	66
	GO TO 15	G	67
13	L=NNI(K)	G	68
	IF (J.GT.1) GO TO 14	G	69
	V(J,2)=SORVAL(K,L)	G	70
	GO TO 15	G	71
14	C(J,2)=SORVAL(K,L)	G	72
15	CONTINUE	G	73
	RETURN	G	74
	END	G	75-

	SUBROUTINE PERIOD (K,J)	H	1
	INTEGER TYPE	H	2
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	H	3
	COMMON /BLOCK7/ IDIMFN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB	H	4
	COMMON /BLOCK8/ V(200,2),C(200,2)	H	5
	COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP	H	6
	COMMON /BLOCK11/ SORVAL(5,100),TIMEPT(5,100),SNSOID(5,3),NNI(5)	H	7
	COMMON /BK13/ ISTEP,OLDVAL(5),SECVAL(5),OLDTIME(5),SECTIME(5),NNJ(H	8
	15)	H	9
	COMMON /BLOCK14/ NP(5)	H	10
	NNN=NNI(K)	H	11
	TIME=TSTART+NIC*H	H	12
1	T=TIME-NNJ(K)*(TIMEPT(K,NNN)-TSTART)	H	13
	IF (T.LF.SECTIME(K)) GO TO 2	H	14
	NP(K)=NP(K)+1	H	15
	IF (NP(K).GT.NNI(K)) GO TO 4	H	16
	NPR=NP(K)	H	17
	OLDTIME(K)=SECTIME(K)	H	18
	SECTIME(K)=TIMEPT(K,NPR)	H	19
	OLDVAL(K)=SECVAL(K)	H	20
	SECVAL(K)=SORVAL(K,NPR)	H	21
2	IF (J.GE.NOEL(1)+1) GO TO 3	H	22
	V(J,2)=OLDVAL(K)+(SECVAL(K)-OLDVAL(K))*(T-OLDTIME(K))/(SECTIME(K)-	H	23
	1OLDTIME(K))	H	24
	GO TO 5	H	25
3	C(J,2)=OLDVAL(K)+(SECVAL(K)-OLDVAL(K))*(T-OLDTIME(K))/(SECTIME(K)-	H	26
	1OLDTIME(K))	H	27
	GO TO 5	H	28
4	NNJ(K)=NNJ(K)+1	H	29
	SECTIME(K)=TIMEPT(K,2)	H	30
	OLDTIME(K)=TIMEPT(K,1)	H	31
	SECVAL(K)=SORVAL(K,2)	H	32
	OLDVAL(K)=SORVAL(K,1)	H	33
	NP(K)=2	H	34
	GO TO 1	H	35
5	RETURN	H	36
	END	H	37-

	SUBROUTINE MATSET (A,NB,NN,NIC)	I	1
	INTEGER CNTSOR	I	2
	INTEGER TEMP	I	3
	INTEGER SORTYPE,CONTYPE	I	4
	INTEGER TYPE	I	5
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	I	6
	COMMON /BLOCK6/ TEMP(7),E(200),GRAD(200),CONST(200)	I	7
	COMMON /BLOCK8/ V(200,2),C(200,2)	I	8
	COMMON /BLOCK9/ SORTYPE(200),CONTYPE(200),KONBRAN(200)	I	9
	COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP	I	10
	COMMON /BLOCK19/ CNTSOR(200)	I	11
	COMMON /BLOCK22/ CK(200)	I	12
	COMMON /BLOCK25/ X(200),Y(200),Z(200,2)	I	13
	DIMENSION A(NB,NB)	I	14
	K=NN-1	I	15
	DO 4 I=1,K	I	16
	IF (TYPE(I).EQ.1HE) GO TO 1	I	17
	IF (TYPE(I).EQ.1HC) GO TO 2	I	18
	IF (TYPE(I).EQ.1HL) GO TO 3	I	19
	CK(I)=0.0	I	20
	GO TO 4	I	21
1	CK(I)=V(I,2)	I	22
	GO TO 4	I	23
2	IF (NIC.EQ.0) CK(I)=COND(I)	I	24
	IF (NIC.NE.0) CK(I)=V(I,1)+CONST(I)*C(I,1)	I	25
	GO TO 4	I	26
3	IF (NIC.EQ.0) CK(I)=0.0	I	27
	IF (NIC.NE.0) CK(I)=-V(I,1)-CONST(I)*C(I,1)	I	28
4	CONTINUE	I	29
	DO 8 I=NN,NB	I	30
	IF (TYPE(I).EQ.1HJ) GO TO 5	I	31
	IF (TYPE(I).EQ.1HC) GO TO 6	I	32
	IF (TYPE(I).EQ.1HL) GO TO 7	I	33
	CK(I)=0.0	I	34
	GO TO 8	I	35
5	CK(I)=C(I,2)	I	36
	GO TO 8	I	37
6	IF (NIC.EQ.0) CK(I)=0.0	I	38
	IF (NIC.NE.0) CK(I)=-C(I,1)-V(I,1)*CONST(I)	I	39
	GO TO 8	I	40
7	IF (NIC.EQ.0) CK(I)=COND(I)	I	41
	IF (NIC.NE.0) CK(I)=C(I,1)+V(I,1)*CONST(I)	I	42
8	CONTINUE	I	43
	DO 29 I=1,K	I	44
	IF (TYPE(I).EQ.1HE) GO TO 9	I	45
	IF (TYPE(I).EQ.1HV) GO TO 11	I	46
	IF (TYPE(I).EQ.1HC) GO TO 18	I	47
	IF (TYPE(I).EQ.1HR) GO TO 19	I	48
	IF (TYPE(I).EQ.1HL) GO TO 22	I	49
	IF (TYPE(I).EQ.1HI) GO TO 23	I	50
	GO TO 29	I	51
9	DO 10 J=1,NB	I	52
	A(I,J)=0.0	I	53
	IF (I.EQ.J) A(I,J)=1.0	I	54
10	CONTINUE	I	55

	GO TO 29	I	56
11	IF (CONTYPE(I).EQ.1HV) GO TO 12	I	57
	GO TO 15	I	58
12	M=CNTSOR(I)	I	59
	DO 13 J=1,K	I	60
	A(I,J)=-F(J,M-K)*CONST(I)	I	61
	IF (I.EQ.J) A(I,J)=1.0+A(I,J)	I	62
13	CONTINUE	I	63
	DO 14 J=NN,NB	I	64
	A(I,J)=0.0	I	65
14	CONTINUE	I	66
	GO TO 29	I	67
15	M=CNTSOR(I)	I	68
	DO 16 J=1,K	I	69
	A(I,J)=0.0	I	70
	IF (I.EQ.J) A(I,J)=1.0	I	71
16	CONTINUE	I	72
	DO 17 J=NN,NB	I	73
	A(I,J)=CONST(I)*F(M,J-K)	I	74
17	CONTINUE	I	75
	GO TO 29	I	76
18	IF (NIC.EQ.0) GO TO 9	I	77
19	DO 20 J=1,K	I	78
	A(I,J)=0.0	I	79
	IF (I.EQ.J) A(I,J)=1.0	I	80
20	CONTINUE	I	81
	DO 21 J=NN,NB	I	82
	A(I,J)=CONST(I)*F(I,J-K)	I	83
21	CONTINUE	I	84
	GO TO 29	I	85
22	IF (NIC.EQ.0) GO TO 9	I	86
	GO TO 19	I	87
23	IF (CONTYPE(I).EQ.1HI) GO TO 26	I	88
	M=CNTSOR(I)	I	89
	DO 24 J=1,K	I	90
	A(I,J)=-CONST(I)*F(J,M-K)	I	91
24	CONTINUE	I	92
	DO 25 J=NN,NB	I	93
	A(I,J)=-F(I,J-K)	I	94
25	CONTINUE	I	95
	GO TO 29	I	96
26	M=CNTSOR(I)	I	97
	DO 27 J=1,K	I	98
	A(I,J)=0.0	I	99
27	CONTINUE	I	100
	DO 28 J=NN,NB	I	101
	A(I,J)=-F(I,J-K)+CONST(I)*F(M,J-K)	I	102
28	CONTINUE	I	103
29	CONTINUE	I	104
	DO 49 I=NN,NB	I	105
	IF (TYPE(I).EQ.1HJ) GO TO 30	I	106
	IF (TYPE(I).EQ.1HI) GO TO 32	I	107
	IF (TYPE(I).EQ.1HC) GO TO 38	I	108
	IF (TYPE(I).EQ.1HR) GO TO 39	I	109
	IF (TYPE(I).EQ.1HL) GO TO 42	I	110

	IF (TYPE(I).EQ.1HV) GO TO 43	I 111
	GO TO 49	I 112
30	DO 31 J=1,NB	I 113
	A(I,J)=0.0	I 114
	IF (I.EQ.J) A(I,J)=1.0	I 115
31	CONTINUE	I 116
	GO TO 49	I 117
32	IF (CONTYPE(I).EQ.1HI) GO TO 35	I 118
	M=CNTSOR(I)	I 119
	DO 33 J=1,K	I 120
	A(I,J)=-F(J,M-K)*CONST(I)	I 121
33	CONTINUE	I 122
	DO 34 J=NN,NB	I 123
	A(I,J)=0.0	I 124
	IF (I.EQ.J) A(I,J)=1.0	I 125
34	CONTINUE	I 126
	GO TO 49	I 127
35	DO 36 J=1,K	I 128
	A(I,J)=0.0	I 129
36	CONTINUE	I 130
	M=CNTSOR(I)	I 131
	DO 37 J=NN,NB	I 132
	A(I,J)=F(M,J-K)*CONST(I)	I 133
	IF (I.EQ.J) A(I,J)=A(I,J)+1.0	I 134
37	CONTINUE	I 135
	GO TO 49	I 136
38	IF (NIC.EQ.0) GO TO 30	I 137
39	DO 40 J=1,K	I 138
	A(I,J)=-F(J,I-K)*CONST(I)	I 139
40	CONTINUE	I 140
	DO 41 J=NN,NB	I 141
	A(I,J)=0.0	I 142
	IF (I.EQ.J) A(I,J)=1.0	I 143
41	CONTINUE	I 144
	GO TO 49	I 145
42	IF (NIC.EQ.0) GO TO 30	I 146
	GO TO 39	I 147
43	IF (CONTYPE(I).EQ.1HI) GO TO 46	I 148
	M=CNTSOR(I)	I 149
	DO 44 J=1,K	I 150
	A(I,J)=F(J,I-K)-F(J,M-K)*CONST(I)	I 151
44	CONTINUE	I 152
	DO 45 J=NN,NB	I 153
	A(I,J)=0.0	I 154
45	CONTINUE	I 155
	GO TO 49	I 156
46	DO 47 J=1,K	I 157
	A(I,J)=F(J,I-K)	I 158
47	CONTINUE	I 159
	M=CNTSOR(I)	I 160
	DO 48 J=NN,NB	I 161
	A(I,J)=CONST(I)*F(M-K,J-K)	I 162
48	CONTINUE	I 163
49	CONTINUE	I 164
	CALL MATINV (A,NB,DETERM,X,Y,Z)	I 165

```
DO 50 I=1,K
V(I,2)=0.0
DO 50 J=1,NB
50 V(I,2)=V(I,2)+A(I,J)*CK(J)
DO 51 I=NN,NB
C(I,2)=0.0
DO 51 J=1,NB
51 C(I,2)=C(I,2)+A(I,J)*CK(J)
RETURN
END
```

```
I 166
I 167
I 168
I 169
I 170
I 171
I 172
I 173
I 174
I 175-
```

```
      SUBROUTINE MATINV (A,N,DETERM,PIVOT,IPIVOT,INDEX)
      MATRIX INVERSION WITH ACCOMPANYING SOLUTION OF LINEAR EQUATIONS
      DIMENSION IPIVOT(N), PIVOT(N), INDEX(N,2), A(N,N)
      EQUIVALENCE (IROW,JROW), (ICOLUM,JCOLUM), (AMAX,T,SWAP)

      C
      C     INITIALIZATION
      C
      C     1      DETERM=1.0
      C     2      DO 2 J=1,N
      C           IPIVOT(J)=0
      C     15     DO 15 I=1,N

      C
      C     SEARCH FOR PIVOT ELEMENT
      C
      C     3      AMAX=0.0
      C     7      DO 7 J=1,N
      C           IF (IPIVOT(J)-1) 3,7,3
      C     6      DO 6 K=1,N
      C           IF (IPIVOT(K)-1) 4,6,19
      C     4      IF (ABS(AMAX)-ABS(A(J,K))) 5,6,6
      C     5      IROW=J
      C           ICOLUM=K
      C           AMAX=A(J,K)
      C     6      CONTINUE
      C     7      CONTINUE
      C           IF (AMAX) 8,20,8
      C     8      IPIVOT(ICOLUM)=IPIVOT(ICOLUM)+1

      C
      C     INTERCHANGE ROWS TO PUT PIVOT ELEMENT ON DIAGONAL
      C
      C     9      IF (IROW-ICOLUM) 9,11,9
      C           DETERM=-DETERM
      C           DO 10 L=1,N
      C             SWAP=A(IROW,L)
      C             A(IROW,L)=A(ICOLUM,L)
      C     10      A(ICOLUM,L)=SWAP
      C     11      INDEX(I,1)=IROW
      C           INDEX(I,2)=ICOLUM
      C           PIVOT(I)=A(ICOLUM,ICOLUM)
      C           DETERM=DETERM*PIVOT(I)

      C
      C     DIVIDE PIVOT ROW BY PIVOT ELEMENT
      C
      C           A(ICOLUM,ICOLUM)=1.0
      C           DO 12 L=1,N
      C     12      A(ICOLUM,L)=A(ICOLUM,L)/PIVOT(I)

      C
      C     REDUCE NON-PIVOT ROWS
      C
      C     13     DO 15 L1=1,N
      C           IF (L1-ICOLUM) 13,15,13
      C           T=A(L1,ICOLUM)
      C           A(L1,ICOLUM)=0.0
```

J 1
J 2
J 3
J 4
J 5
J 6
J 7
J 8
J 9
J 10
J 11
J 12
J 13
J 14
J 15
J 16
J 17
J 18
J 19
J 20
J 21
J 22
J 23
J 24
J 25
J 26
J 27
J 28
J 29
J 30
J 31
J 32
J 33
J 34
J 35
J 36
J 37
J 38
J 39
J 40
J 41
J 42
J 43
J 44
J 45
J 46
J 47
J 48
J 49
J 50
J 51
J 52
J 53
J 54
J 55

	DO 14 L=1,N	J	56
14	A(L1,L)=A(L1,L)-A(ICOLUM,L)*T	J	57
15	CONTINUE	J	58
C		J	59
C	INTERCHANGE COLUMNS	J	60
C		J	61
	DO 18 I=1,N	J	62
	L=N+1-I	J	63
	IF (INDEX(L,1)-INDEX(L,2)) 16,18,16	J	64
16	JROW=INDEX(L,1)	J	65
	JCOLUM=INDEX(L,2)	J	66
	DO 17 K=1,N	J	67
	SWAP=A(K,JROW)	J	68
	A(K,JROW)=A(K,JCOLUM)	J	69
	A(K,JCOLUM)=SWAP	J	70
17	CONTINUE	J	71
18	CONTINUE	J	72
19	RETURN	J	73
20	DETERM=0.	J	74
	RETURN	J	75
	END	J	76-

	SUBROUTINE READOUT	K	1
	INTEGER TEMP	K	2
	INTEGER SORTYPE,CONTYPE	K	3
	INTEGER TYPE	K	4
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	K	5
	COMMON /BLOCK5/ IOUT(200),NOUT(200),ITEST(200)	K	6
	COMMON /BLOCK6/ TEMP(7),E(200),GRAD(200),CONST(200)	K	7
	COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB	K	8
	COMMON /BLOCK8/ V(200,2),C(200,2)	K	9
	COMMON /BLOCK9/ SORTYPE(200),CONTYPE(200),KONBRAN(200)	K	10
	COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP	K	11
	COMMON /BLOCK15/ NIT,JOUT,NGRAPH,NALLOUT	K	12
	COMMON /BLOCK16/ GRAF(200,5),JGRAPH(5),IGRAPH(5),NPRINT,SCALE,NITT	K	13
	COMMON /BLOCK18/ VAROUT(200)	K	14
	N=NN-1	K	15
	DO 4 I=1,JOUT	K	16
	K=NOUT(I)	K	17
	IF (NOUT(I).LT.NN) GO TO 2	K	18
	IF (ITEST(I).EQ.1) GO TO 1	K	19
	VAROUT(I)=V(K,2)	K	20
	GO TO 4	K	21
1	VAROUT(I)=C(K,2)/SCALE	K	22
	GO TO 4	K	23
2	IF (ITEST(I).EQ.0) GO TO 3	K	24
	VAROUT(I)=C(K,2)/SCALE	K	25
	GO TO 4	K	26
3	VAROUT(I)=V(K,2)	K	27
4	CONTINUE	K	28
	TIME=H*NIC+TSTART	K	29
	IF (NIC.EQ.0) PRINT 6	K	30
	PRINT 7, TIME	K	31
	DO 5 I=1,JOUT	K	32
	A=7HVOLTAGE	K	33
	IF (ITEST(I).EQ.1) A=7HCURRENT	K	34
	PRINT 8, IOUT(I),A,VAROUT(I)	K	35
5	CONTINUE	K	36
	RETURN	K	37
C		K	38
6	FORMAT (1H1)	K	39
7	FORMAT (//////,10X,*TIME = *,E15.5)	K	40
8	FORMAT (1H0,10X,*BRANCH*,I5,5X,A7,10X,E15.5)	K	41
	END	K	42-

	SUBROUTINE GRAPH	L	1
	INTEGER TYPE	L	2
	COMMON /BLOCK1/ ANP(200),NP(200)	L	3
	COMMON /BLOCK3/ TYPE(200),VALUE(200),F(49,151),NOEL(7)	L	4
	COMMON /BLOCK4/ ITBRAN(200),LEAVT(200),LENTT(200)	L	5
	COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB	L	6
	COMMON /BLOCK8/ V(200,2),C(200,2)	L	7
	COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP	L	8
	COMMON /BLOCK15/ NIT,JOUT,NGRAPH,NALLOUT	L	9
	COMMON /BLOCK16/ GRAF(200,5),JGRAPH(5),IGRAPH(5),NPRINT,SCALE,NITT	L	10
	COMMON /BLOCK21/ NST(5)	L	11
1	DO 3 I=1,NGRAPH	L	12
	K=NST(I)	L	13
	IF (JGRAPH(I).EQ.0) GO TO 2	L	14
	GRAF(NPRINT,I)=C(K,2)/SCALE	L	15
	GO TO 3	L	16
2	GRAF(NPRINT,I)=V(K,2)	L	17
3	CONTINUE	L	18
	IF (NPRINT.LT.200.AND.(NITER-NIC).GE.NSTEP) RETURN	L	19
	DO 9 I=1,NGRAPH	L	20
	PRINT 11	L	21
	A=7HVOLTAGE	L	22
	IF (JGRAPH(I).EQ.1) A=7HCURRENT	L	23
	PRINT 10, IGRAPH(I),A	L	24
	AMAX=GRAF(1,I)	L	25
	AMAX=ABS(AMAX)	L	26
	DO 4 J=2,NPRINT	L	27
	A=GRAF(J,I)	L	28
	A=ABS(A)	L	29
	IF (A.GT.AMAX) AMAX=A	L	30
4	CONTINUE	L	31
	DO 5 J=1,NPRINT	L	32
	NP(J)=GRAF(J,I)*50.0/AMAX+51.0	L	33
5	CONTINUE	L	34
	DO 6 J=1,101	L	35
	ANP(J)=1H.	L	36
6	CONTINUE	L	37
	PRINT 12, (ANP(J),J=1,101)	L	38
	DO 7 J=1,102	L	39
	ANP(J)=1H	L	40
7	CONTINUE	L	41
	ANP(51)=1H.	L	42
	DO 8 KK=1,NPRINT	L	43
	LL=NP(KK)	L	44
	IF (LL.GE.51) LL=LL+1	L	45
	ANP(LL)=1H+	L	46
	TIME=TSTART+NSTEP*KK*H-H	L	47
	PRINT 13, TIME,GRAF(KK,I),(ANP(J),J=1,102)	L	48
	ANP(LL)=1H	L	49
8	CONTINUE	L	50
9	CONTINUE	L	51
	NGRAPH=201	L	52
	RETURN	L	53
C		L	54
10	FORMAT (1H0,30X,*BRANCH*,I4,5X,A7)	L	55

```
11  FORMAT (1H1)
12  FORMAT (1H0,2X,*TIME*,10X,*VALUE*,6X,101A1)
13  FORMAT (1HZ,E11.4,2X,E11.4,3X,102A1)
    END
```

```
L 56
L 57
L 58
L 59-
```

SUBROUTINE ALLOUT

COMMON /BLOCK7/ IDIMEN,ALPHA,FUNCT,NIC,NITER,H,EPS,NN,NB

COMMON /BLOCK8/ V(200,2),C(200,2)

COMMON /BLOCK10/ COND(200),IDEL,TSTART,TEND,NSTEP

COMMON /BLOCK16/ GRAF(200,5),JGRAPH(5),IGRAPH(5),NPRINT,SCALE,NITT

COMMON /BLOCK18/ A(200)

DO 1 I=NN,NB

A(I)=C(I,2)/SCALE

CONTINUE

N=NN-1

TIME=(TSTART+H*NIC)

PRINT 2, TIME

PRINT 3, (V(I,2),I=1,N)

PRINT 4, (A(I),I=NN,NB)

RETURN

C

2 FORMAT(1H0,///,* TIME = *,E15.5)

3 FORMAT(1H0,*THESE ARE THE TREE BRANCH VOLTAGES*,//,10(3X,E12.5))

4 FORMAT (1H0, * THESE ARE THE LINK CURRENTS *,//,10(3X,E12.5))

END

M 1
M 2
M 3
M 4
M 5
M 6
M 7
M 8
M 9
M 10
M 11
M 12
M 13
M 14
M 15
M 16
M 17
M 18
M 19
M 20-

APPENDIX E

General Comments Regarding Use of CANINE:

1. Number of nodes cannot exceed 50.
2. Number of branches cannot exceed 200.
3. Cannot exceed 5 arbitrary or periodic independent sources, and cannot exceed 5 sinusoidal or exponential sources. There is no limit on the number of constant independent sources. We can have at most 100 time points to describe an arbitrary independent source.
4. Cannot exceed 5 graphical outputs.
5. There is an internal limit of 200 output points per graph.
6. Branch and node numbering is arbitrary, but branch numbers cannot exceed three digits, and node numbers cannot exceed two digits.
7. Core requirements:

Since our inversion scheme requires the storing of an $NB \times NB$ matrix, it would, in general, be inconvenient to always dimension the above matrix 200×200 .

Thus, to save core, one need only replace the DIMENSION statement in the MAIN program by

DIMENSION HH(N, N)

where N is the maximum number of branches to be encountered in the network(s) to be solved.

With the above dimensioning procedure, the core requirements for CANINE are, approximately,

$$27000 + N^2 \text{ (decimal)}$$

storage locations.

8. There must be at least one branch which is not an independent source, in any given network.
9. CANINE can handle zero valved R's, L's and C's as long as there are no loops of zero valved inductances or resistances (short circuits), and no cutsets of zero valved capacitances (open circuits). In this context, independent voltage sources are equivalent to short circuits, and independent current sources are equivalent to open circuits.
10. H, the time increment, cannot be zero for networks containing reactive elements (L's and C's).
11. CANINE can be used for batch processing; simply stack data card sets, for the networks to be solved, one behind the other, ensuring that the last card in the stack is a blank card.
12. Zero is not a valid branch or node number.
13. The output voltage and current units are always volts and amperes respectively.

BIBLIOGRAPHY

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