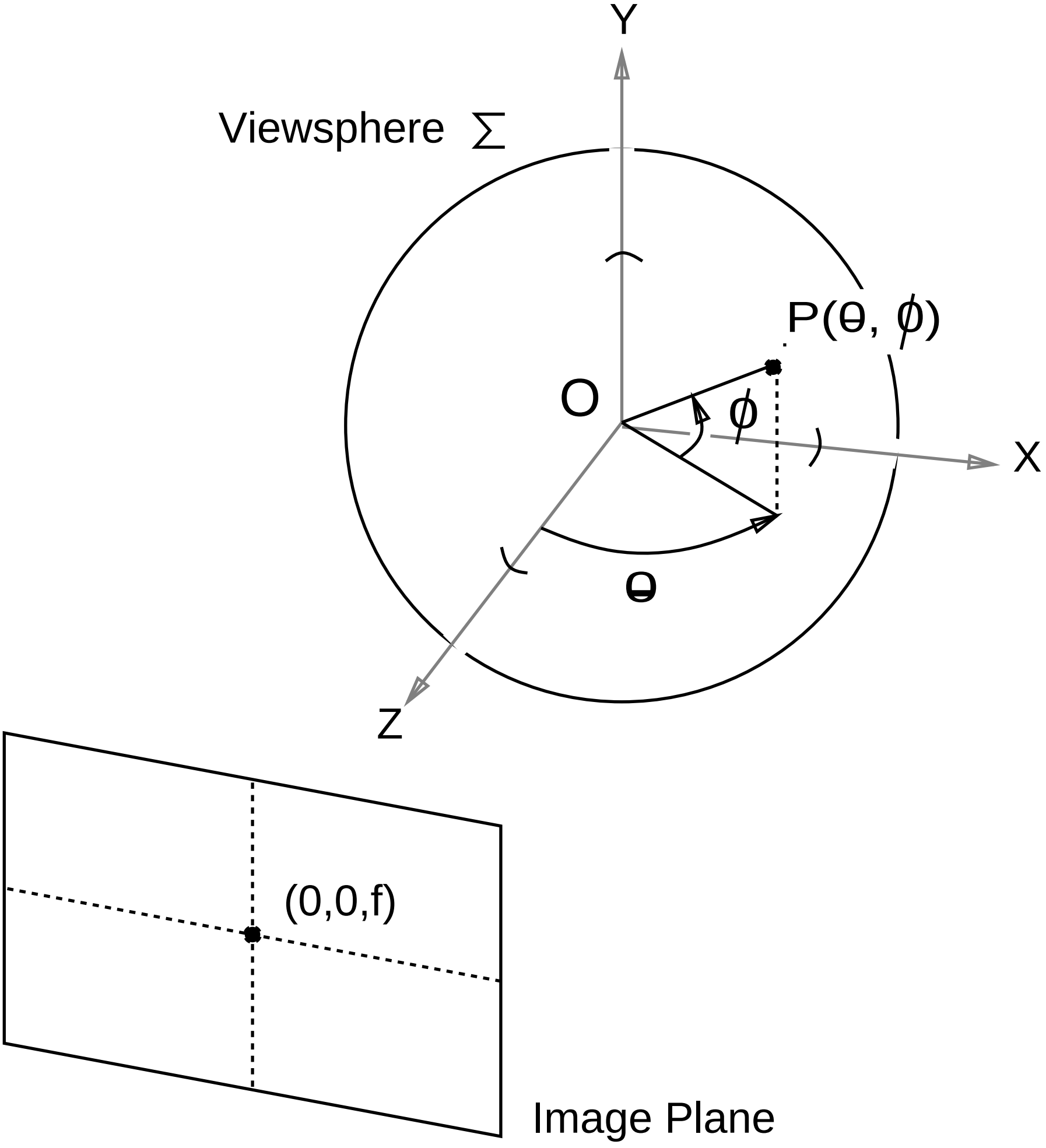
Y
Viewsphere ∑
P(θ, ϕ)
O
ϕ
X
θ
Z
(0,0,f)
Image Plane